Optimization

ASU Textbook Chapter 9

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Machine-dependent code generation

- For some compiler, the intermediate code is a pseudo code of a virtual machine.
 - Interpreter of the virtual machine is invoked to execute the intermediate code.
 - No machine-dependent code generation is needed.
 - usually with great overhead.
 - Example:
 - ▷ Pascal: P-code for the virtual P machine.
 - ▷ JAVA: Byte code for the virtual JAVA machine.

Machine-dependent issues (1/2)

- Input and output format:
 - The format of the intermediate code and the target program.
- Memory management:
 - Alignment, indirect addressing, paging, segment,
 - Those you learned from your assembly language class.
- Instruction cost:
 - Special machine instructions to speed up execution.
 - Example:
 - ▷ Increment by 1.
 - ▶ Multiplying or dividing by 2.
 - ▷ Bit-wise manipulation.
 - ▷ Operators applied on a block of memory space.

• Pick the fastest instruction combination for a certain target machine.

Machine-dependent issues (2/2)

Register allocation:

- C language allows the user to management a pool of registers.
- Some language leaves the task to compiler.
- Idea: save mostly used intermediate result in a register. However, finding an optimal solution for using a limited set of registers is NP-hard.
- Example:
 - t := a + b load R0,a load R0,a load R1,b add R0,b add R0,R1 store R0,T store R0,T
- Solutions using heuristics: similar to swapping.

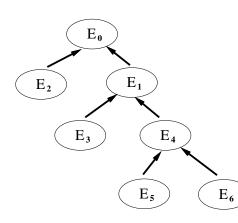
• Optimization.

Optimization

Issues:

- In an expression, assume its dependence graph is given.
- We can evaluate it using any topological ordering.
- There are many legal topological orderings.
- Picking a right one will increase its efficiency.

Example:



order#1	reg#	order#2	reg#
E2	1	E6	1
E3	2	E5	2
E5	3	E4	1
E6	4	E3	2
E4	3	E1	1
E1	2	E2	2
EO	1	EO	1

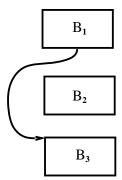
On a machine with only 2 free registers, some of the intermediate results in ordering 1 must be stored in temporary space.

• STORE/LOAD takes time.

Basic blocks and flow graphs

- Assumption: the input is an intermediate code program.
- Basic block: a sequence of intermediate code such that
 - Jump statements, if any, are at the end of the sequence.
 - Codes in other basic block can only jump to the beginning of this sequence, but not in the middle.
 - Example:
 - $\begin{array}{l} \triangleright \ t_1 := a \ast a \\ \triangleright \ t_2 := a \ast b \\ \triangleright \ t_3 := 2 \ast t_2 \\ \triangleright \ \textbf{goto outter} \end{array}$

Flow graph: where nodes are basic blocks and edges are flow of control.



How to find basic blocks

- How to find leaders, which are the first statements of basic blocks.
 - The first statement of a program is a leader.
 - For all conditional and unconditional goto:
 - ▷ Its target is a leader.
 - ▷ Its next statement is also a leader.
- Using leaders to partition the program into basic blocks.
- Ideas for optimization:
 - Two basic blocks are equivalent if they compute the same expressions.
 - Use transformation techniques below to perform machine-dependent optimization.

Finding basic blocks — examples

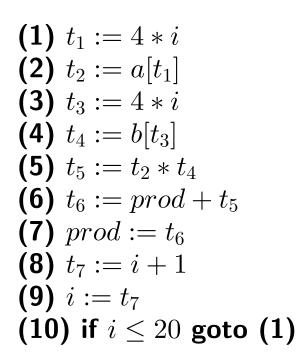
Example: Three-address code for computing the dot product of two vectors a and b.

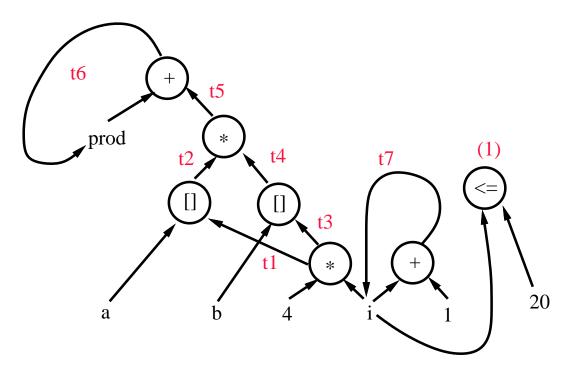
```
> prod := 0
> i := 1
> loop: t_1 := 4 * i
> t_2 := a[t_1]
> t_3 := 4 * i
> t_4 := b[t_3]
> t_5 := t_2 * t_4
> t_6 := prod + t_5
> prod := t_6
> t_7 := i + 1
> i := t_7
> if i \leq 20 goto loop
> ...
```

There are three blocks in the above example.

DAG representation of a basic block

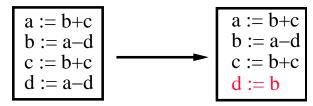
- Inside a basic block:
 - Expressions can be expressed using a DAG that is similar to the idea of a dependence graph.
 - Graph might not be connected.
- Example:





Structure-preserving transformations

Techniques: using the flow graph and DAG representation of basic blocks.



- Common sub-expression elimination.
- Dead-code elimination: remove unreachable codes.
- Renaming temporary variables: better usage of registers and avoiding using unneeded temporary variables.
- Interchange of two independent adjacent statements, which might be useful in discovering the above three transformations.

```
Same expressions that are too far away to store E<sub>1</sub> into a register.
t1 := E1
Example: ...
tn := E1
Note: two dependent statements cannot be exchanged.
t1 := a + b
Example: ...
tn := t1 + c
```

Algebraic transformations

Algebraic identities:

- x + 0 = 0 + x = x
- x 0 = x
- x * 1 = 1 * x = x
- x/1 = x

Reduction in strength:

- $x^2 = x * x$
- 2.0 * x = x + x
- x/2 = x * 0.5

Constant folding:

• 2 * 3.14 = 6.28

Standard representation for subexpression by commutativity and associativity:

- n * m = m * n.
- *b* < *a* == *a* > *b*.

Peephole optimization (1/2)

Idea:

- Statement by statement translation might generate redundant codes.
- Locally improve the target code performance by examine a short sequence of target instructions (called a peephole) and do optimization on this sequence.
- Complexity depends on the "window size".
- Techniques:
 - Redundant loads and stores:
 - \triangleright **MOV** R_0, a
 - \triangleright **MOV** a, R_0
 - Unreachable codes:
 - ▶ An unlabeled instruction immediately following an unconditional jump may be removed.
 - \triangleright If statements based on constants: If debug then \cdots .

Peephole optimization (2/2)

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More techniques:

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• Flow of control optimization:

goto L1 goto L2

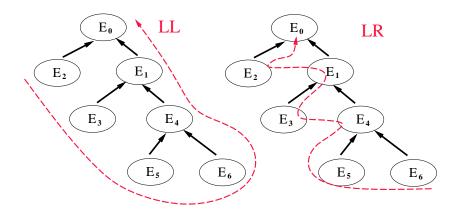
L1: goto L2

L1: goto L2

- Algebraic simplification.
- Use of special machine idioms.
- Better usage of registers.

Correctness after optimization

When side effects are expected, different evaluation order may produce different results for expressions.



- Assume E_5 is a procedure call with the side effect of changing some values in E_6 .
- *LL* and *LR* parsing produces different results.
- Watch out precisions when doing algebraic simplification.
 - if (x = 321.123456789 321.123456788) > 0 then \cdots
- Need to make sure code before and after optimization produce the same result.
- Complications arise when debugging is involved.