

Run Time Storage Organization

ASU Textbook Chapter 7.1–7.4, and 7.7–7.8

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Preliminaries

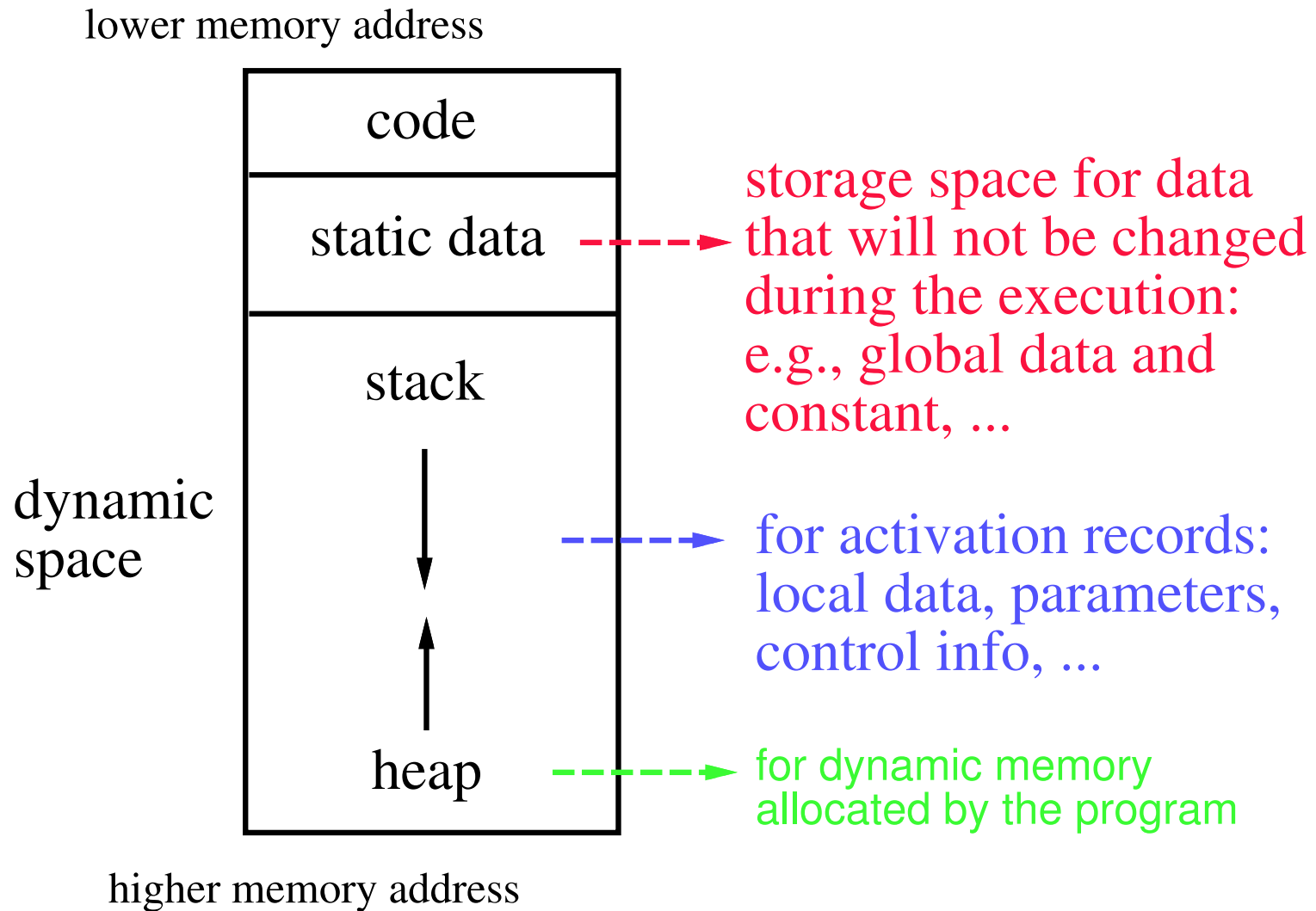
- During the execution of a program, the same name in the source can denote different data objects in the computer.
- The allocation and deallocation of data objects is managed by the **run-time support package**.
- **Terminologies:**
 - **name** → **storage space**: the mapping of names to storage spaces is called an **environment**.
 - **storage space** → **value**: the current value of a storage space is called its **state**.
 - The association of a name to a storage location is called a **binding**.
- Each execution of a procedure is called an **activation**.
 - If it is a recursive procedure, then several of its activations may exist at the same time.
 - **Life time**: the time between the first and last steps in a procedure.
 - A recursive procedure needs not to call itself directly.

Activation record

returned value
actual parameters
optional control link
optional access link
saved machine status
local data
temporaries

- **Activation record: data about an execution of a procedure.**
 - **Parameters:**
 - ▷ *Formal parameters:* the declaration of parameters.
 - ▷ *Actual parameters:* the values of parameters for this activation.
 - **Links:**
 - ▷ *Control (or dynamic) link:* a pointer to the activation record of the caller.
 - ▷ *Access (or static) link:* a pointer to places of non-local data,

General run time storage layout



Issues in storage allocation

- There are two different approaches for run time storage allocation.
 - Static allocation.
 - Dynamic allocation.
- Need to worry about how variables are stored.
 - That is the management of activation records.
- Need to worry about how variables are accessed.
 - Global variables.
 - Locally declared variables , that is the ones allocated within the current activation record.
 - Non-local variables , that is the ones declared and allocated in other activation records and can be accesses here.
 - ▷ *Non-local variables are different from global variables.*

Static storage allocation (1/3)

- **Static allocation:** uses no stack and heap.
 - **Strategies:**
 - ▷ *For each procedure in the program, allocate a space for its activation record.*
 - ▷ *A.R.'s can be allocated in the static data area.*
 - ▷ *Names bound to locations at compiler time.*
 - ▷ *Every time a procedure is called, a name always refer to the same pre-assigned location.*
 - Used by simple or early programming languages.
- **Disadvantages:**
 - No recursion.
 - Waste lots of space when inactive.
 - No dynamic allocation.
- **Advantages:**
 - No stack manipulation or indirect access to names, i.e., faster in accessing variables.
 - Values are retained from one procedure call to the next if block structure is not allowed.
 - ▷ *For example: static variables in C.*

Static storage allocation (2/3)

■ On procedure calls,

● the calling procedure:

▷ *First evaluate arguments.*

▷ *Copies arguments into parameter space in the A.R. of called procedure.*

Convention: call that which is passed to a procedure arguments from the calling side, and parameters from the called side.

▷ *May save some registers in its own A.R.*

▷ *Jump and link: jump to the first instruction of called procedure and put address of next instruction (return address) into register RA (the return address register).*

● the called procedure:

▷ *Copies return address from RA into its A.R.'s return address field.*

▷ *control link := address of the previous A.R.*

▷ *May save some registers.*

▷ *May initialize local data.*

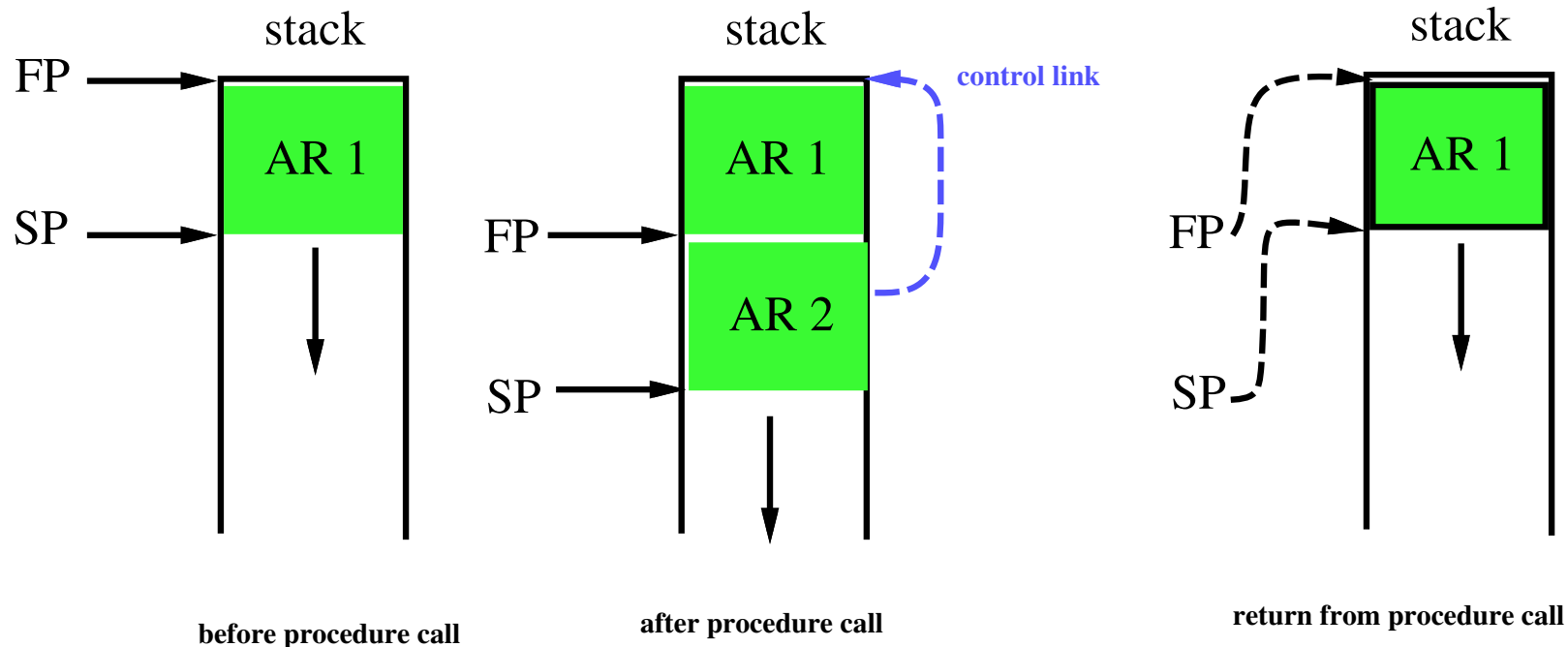
Static storage allocation (3/3)

- **On procedure returns,**
 - **the called procedure:**
 - ▷ *Restores values of saved registers.*
 - ▷ *Jump to address in the return address field.*
 - **the calling procedure:**
 - ▷ *May restore some registers.*
 - ▷ *If the called procedure is actually a function, that is the one that returns values, put the return value in the appropriate place.*

Dynamic storage allocation for STACK (1/3)

■ Stack allocation:

- Each time a procedure is called, a new A.R. is pushed onto the stack.
- A.R. is popped when procedure returns.
- A register (SP for stack pointer) points to top of stack.
- A register (FP for frame pointer) points to start of current A.R.



Dynamic storage allocation for STACK (2/3)

■ On procedure calls,

● the calling procedure:

- ▷ *May save some registers (in its own A.R.).*
- ▷ *May set optional access link (push it onto stack).*
- ▷ *Pushes parameters onto stack.*
- ▷ *Jump and Link: jump to the first instruction of called procedure and put address of next instruction into register RA.*

● the called procedure:

- ▷ *Pushes return address in RA.*
- ▷ *Pushes old FP (control link).*
- ▷ *Sets new FP to old SP.*
- ▷ *Sets new SP to be old SP + (size of parameters) + (size of RA) + (size of FP). (These sizes are computed at compile time.)*
- ▷ *May save some registers.*
- ▷ *Push local data (maybe push actual data if initialized or maybe just their sizes from SP)*

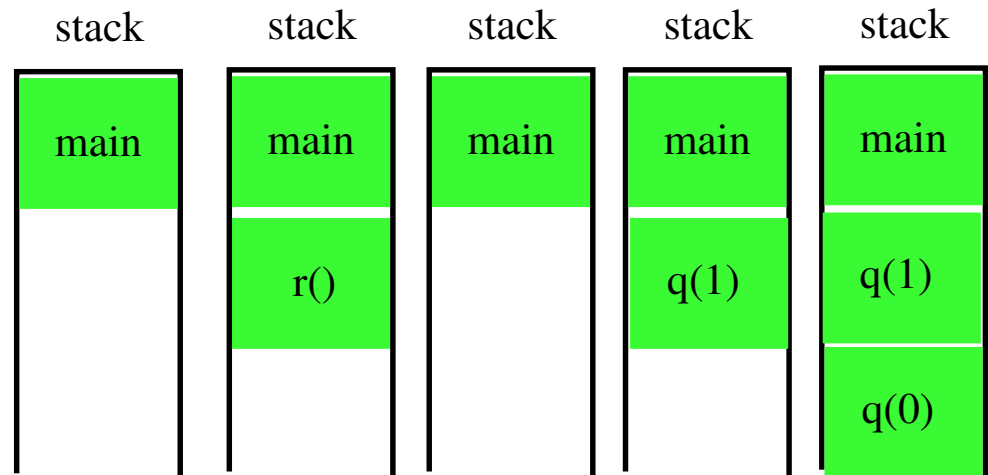
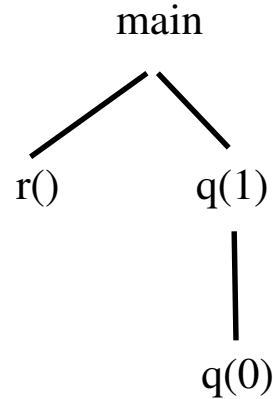
Dynamic storage allocation for STACK (3/3)

- **On procedure returns,**
 - **the called procedure:**
 - ▷ *Restore values of saved registers if needed.*
 - ▷ *Loads return address into special register RA.*
 - ▷ *Restores SP ($SP := FP$).*
 - ▷ *restore FP ($FP := \text{saved FP}$).*
 - ▷ *return.*
 - **the calling procedure:**
 - ▷ *May restore some registers.*
 - ▷ *If it is in fact a function that was called, put the return value into the appropriate place.*

Activation tree

- Use a tree structure to record the changing of the activation records.
- Example:

```
main{  
    r();  
    q(1);  
}  
  
r{  
    ...  
}  
  
q(int i)  
{  
    if(i>0) then q(i-1);  
}
```



Dynamic storage allocation for HEAP

- **Storages requested from programmers during execution:**
 - **Example:**
 - ▷ *PASCAL: new and free.*
 - ▷ *C: malloc and free.*
 - **Issues:**
 - ▷ *Garbage collection.*
 - ▷ *Segmentation.*
 - ▷ *Dangling reference.*
- **More or less O.S. issues.**

Run time variable accesses

■ Global variables:

- Access by using names.
- Addresses known at compile time.

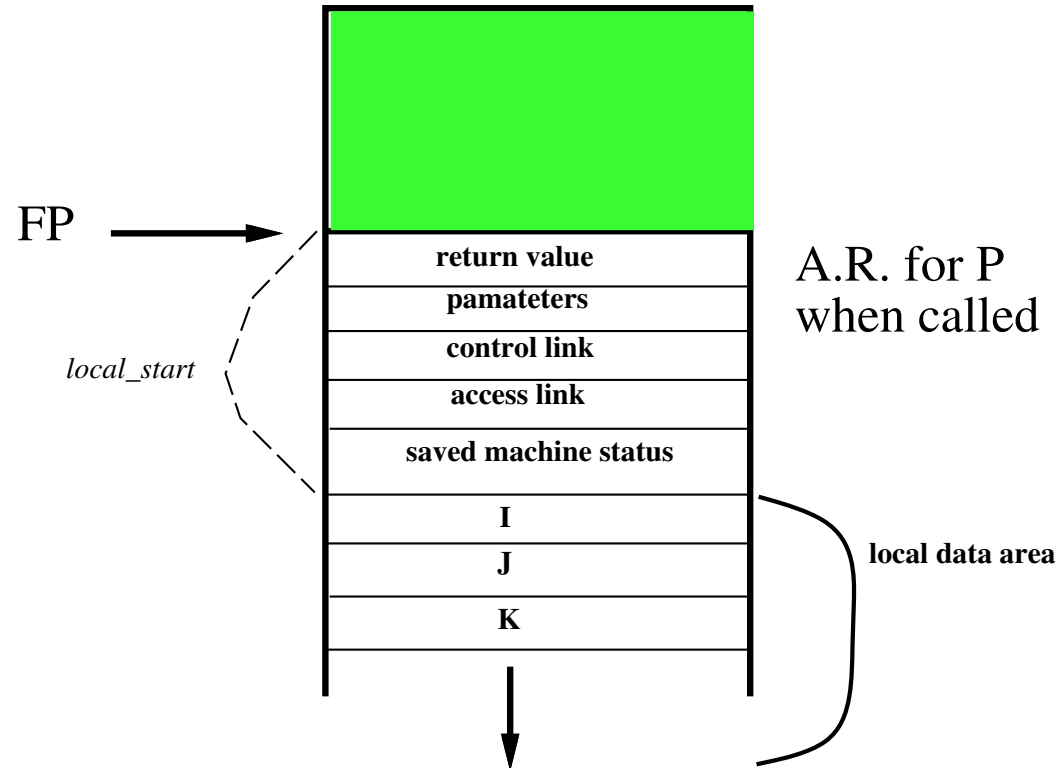
■ Local variables:

- Stored in the activation record of declaring procedure.
- Access a local variable v in a procedure P by $offset(v)$ from the frame pointer (FP).

- ▷ *Let $local_start(P)$ be the amount of spaces used by data in the activation record of procedure P that are allocated before the local data area.*
- ▷ *The value $local_start(P)$ can be computed at compile time.*
- ▷ *The value $offset(v)$ is the amount of spaces allocated to local variables declared before v .*
- ▷ *The address of v is $FP + local_start(P) + offset(v)$.*
- ▷ *The actual address is only known at run time, depending on the value of FP.*

Run time variable accesses – example

```
int P()  
{  
  int I,J,K;  
  ...  
}
```



- **Address of J is $FP + local_start(P) + offset(v)$.**
- **$offset(v)$ is $1 * sizeof(int)$ and is known at compile time.**
- **$local_start(P)$ is known at compile time.**
- **Actual address is only known at run time, i.e., depends on the value of FP.**

Accessing non-local variables

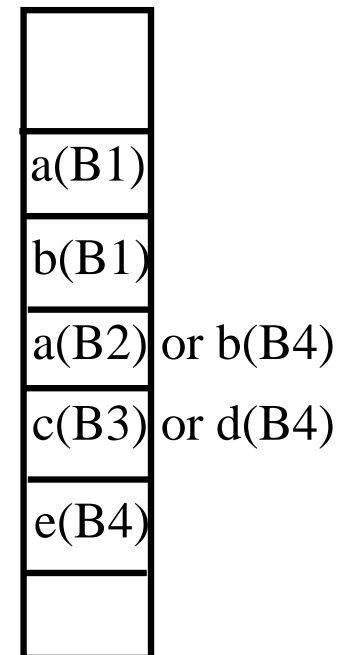
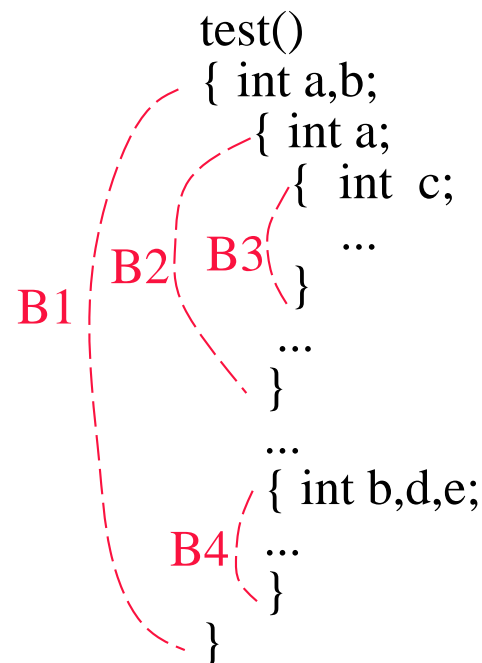
- **Two scoping rules for accessing non-local data.**
 - **Lexical or static scoping.**
 - ▷ *PASCAL, C and FORTRAN.*
 - ▷ *The correct address of a non-local name can be determined at compile time by checking the syntax.*
 - ▷ *Can be with or without block structures.*
 - ▷ *Can be with or without nested procedures.*
 - **Dynamic scoping.**
 - ▷ *LISP.*
 - ▷ *A use of a non-local variable corresponds to the declaration in the “most recently called, still active” procedure.*
 - ▷ *The question of which non-local variable to use cannot be determined at compile time. It can only be determined at run-time.*

Lexical scoping with block structures

- **Block:** a statement containing its own local data declaration.
- **Scoping is given by the following so called most closely nested rule.**
 - The scope of a declaration in a block B includes B itself.
 - If x is used in B , but not declared in B , then we refer to x in a block B' , where
 - ▷ B' has a declaration x , and
 - ▷ B' is more closely nested around B than any other block with a declaration of x .

Lexical scoping without nested procedures

- Nested procedure: a procedure that can be declared within another procedure.
- If a language does not allow nested procedures, then
 - a variable is either global, or is local to the procedure containing it;
 - at runtime, all the variables declared (including those in blocks) in a procedure are stored in its A.R., with possible overlapping;
 - during compiling, proper offset for each local data is calculated using information known from the block structure.



Lexical scoping with nested procedures (1/3)

- In a program with lexical scoping and nested procedures, what are the procedures that can be called in a given procedure Q_0 ?
 - The procedure Q_1 who declares Q_0 .
 - The procedure Q_i who declares Q_{i-1} , $i > 0$.
 - The procedure P_i whom is declared together with, but before, Q_i , $i > 0$
- In a procedure declaration tree, Q_0 can call any procedure that is its direct ancestor or the older siblings of its direct ancestor.
- A procedure can only access the variables that is global in a procedure that is its direct ancestor.
 - When you call a procedure, a variable name follows the lexical scoping rule.
 - Use the access link to link to the procedure that is lexically enclosing the called procedure.
 - Need to set up the access link properly to access the right storage space.

Lexical scoping with nested procedures (2/3)

procedure main

procedure a1

procedure s1

procedure a2

procedure b1

procedure q1

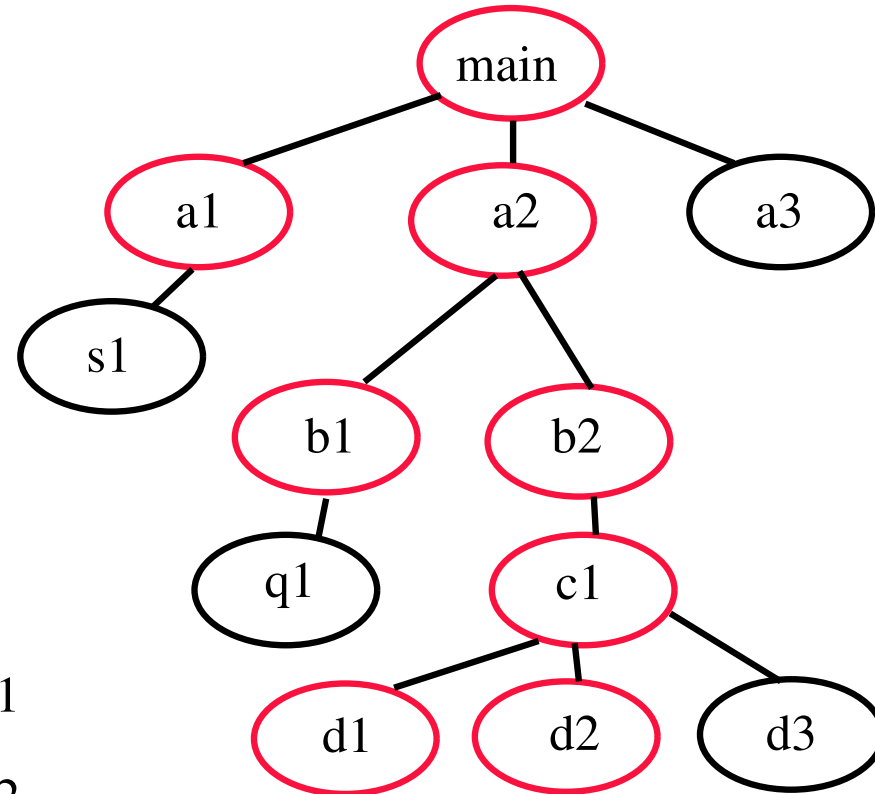
procedure b2

procedure c1

procedure d1

procedure d2

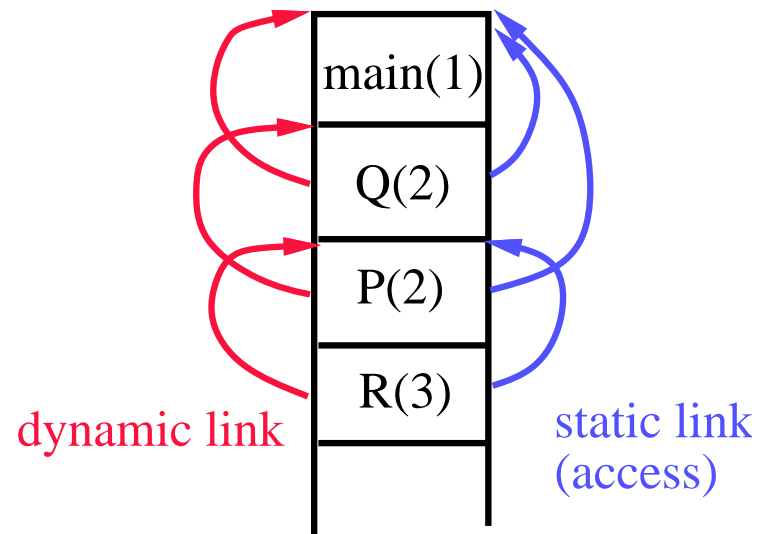
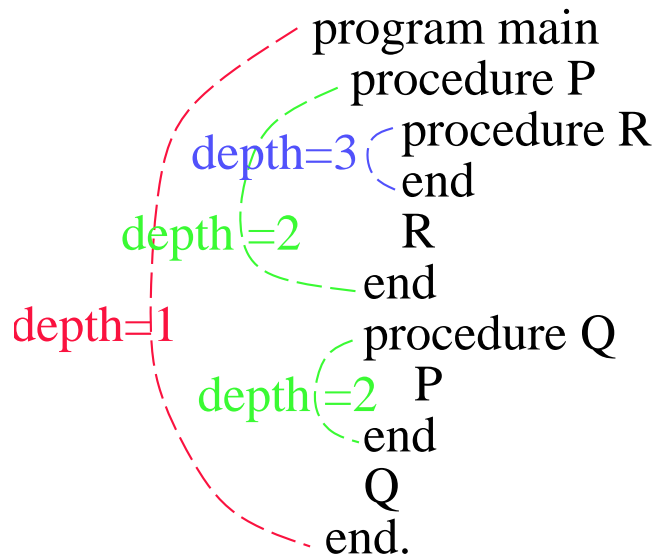
procedure d3



Lexical scoping with nested procedures (3/3)

■ Nesting depth:

- depth of main program = 1.
- add 1 to depth each time entering a nested procedure.
- substrate 1 from depth each time existing from a nested procedure.
- Each variable is associated with a nesting depth.
- Assume in a depth- h procedure, we access a variable at depth k , then
 - ▷ $h \geq k$.
 - ▷ follow the access (static) link $h - k$ times, and then use the offset information to find the address.



Algorithm for setting the links

- The control link is set to point to the A.R. of the calling procedure.
- How to properly set the access link at compile time.
 - Procedure p at depth n_p calls procedure x at depth n_x :
 - If $n_p < n_x$, then x is enclosed in p and $n_p = n_x - 1$.
 - ▷ *Same with setting the control link.*
 - If $n_p \geq n_x$, then it is either a recursive call or calling a previously declared procedure.
 - ▷ *Observation: go up the access link once, then the depth is decreased by 1.*
 - ▷ *Hence, the access link of x is the access link of p going up $n_p - n_x + 1$ times.*

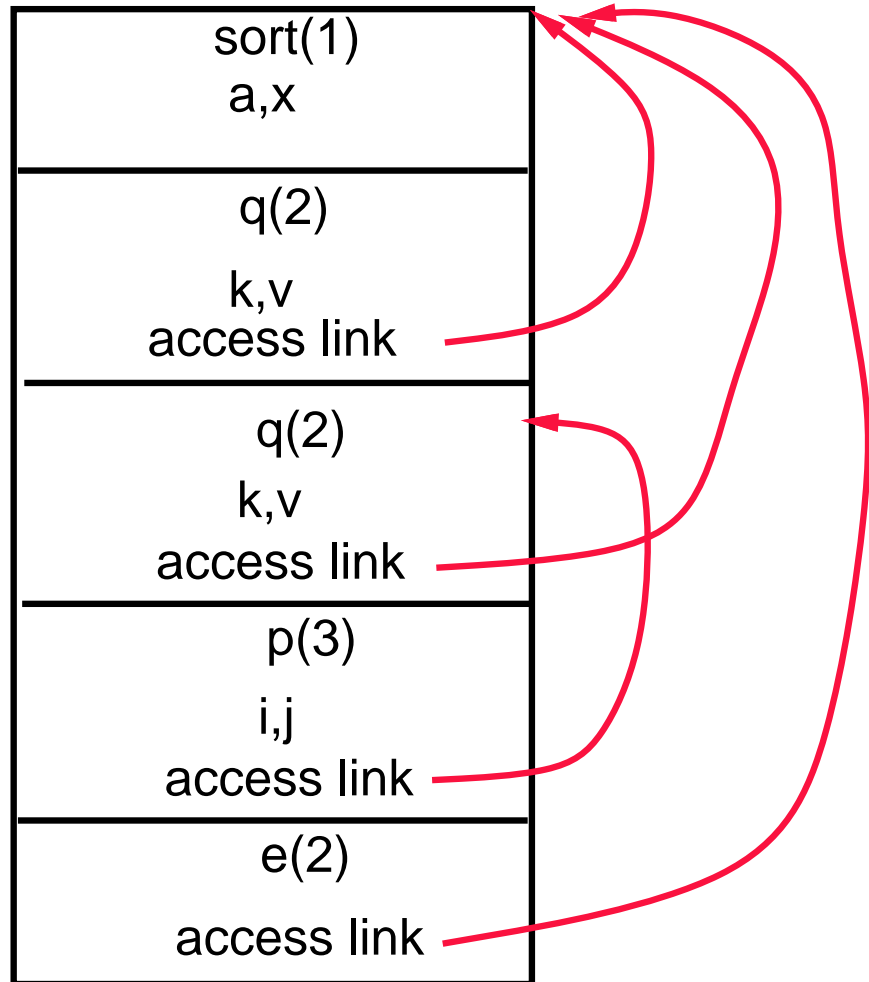
Example

```
Program sort
  var a: array[0..10] of int;
      x: int;
  procedure r
    var i: int;
    begin ... r
  end

  procedure e(i,j)
    begin ... e
      a[i] <-> a[j]
    end

  procedure q
    var k,v: int;
    procedure p
      var i,j;
      begin ... p
        call e
      end
    begin ... q
      call q or p
    end

  begin ... sort
    call q
  end
```



Accessing non-local data using DISPLAY

■ Idea:

- Maintain a global array called DISPLAY.
 - ▷ Using registers if available.
 - ▷ Otherwise, stored in the static data area.
- When procedure P at nesting depth k is called,
 - ▷ $DISPLAY[1], \dots, DISPLAY[k-1]$ hold pointers to the A.R.'s of the most recent activation of the $k - 1$ procedures that lexically enclose P .
 - ▷ $DISPLAY[k]$ holds pointer to P 's A.R.
 - ▷ To access a variable with declaration at depth x , use $DISPLAY[x]$ to get to the A.R. that holds x , then use the usual offset to get x itself.
 - ▷ Size of DISPLAY equals maximum nesting depth of procedures.
- Bad for languages allow recursions.

■ To maintain the DISPLAY

- When a procedure at nesting depth k is called
 - ▷ Save the current value of $DISPLAY[k]$ in the save-display field of the new A.R.
 - ▷ Set $DISPLAY[k]$ to point to the new A.R., i.e., to its save-display field.
- When the procedure returns, restore $DISPLAY[k]$ using the value saved in the save-display field.

Access links v.s. DISPLAY

- **Time and space trade-off.**
 - **Access links require more time (at run time) to access non-local data. Especially when non-local data are many nesting levels away.**
 - **DISPLAY probably require more space (at run time).**
 - **Code generated using DISPLAY is simpler.**

Dynamic scoping

- **Dynamic scoping:** a use of a non-local variable refers to the one declared in the “most recently called, still active” procedure.
- The question of which non-local variable to use cannot be determined at compile time.
- It can only be determined at run time.
- May need symbol tables at run time.
- Two ways to implement non-local accessing under dynamic scoping.
 - Deep access.
 - Shallow access.

Dynamic scoping – Example

```
program main
  procedure test
    var x : int;
  begin
    x := 30;
    call DeclaresX;
    call UsesX;
  end
  procedure DeclaresX
    var x: int;
  begin
    x := 100;
    call UsesX;
  end
  procedure UsesX
  begin
    write(x);
  end
begin
  call test;
end
```

■ Code:

- Which x is it in the procedure UsesX?
- If we were to use static scoping, this is not a legal statement; No enclosing scope declares x .

Deep access

- **Def:** given a use of a non-local variable, use control links to search back in the stack for the most recent A.R. that contains space for that variable.
 - Note: this requires that to be possible to tell the set of variables stored in each A.R.
 - Need to use the symbol tables at run time.

Shallow access

■ Idea:

- Maintain a current list of variables.
- Space is allocated (in registers or in the static data area) for every possible variable name that is in the program (i.e., one space for variable x even if there are several declarations of x in different procedures).
- For every reference to x , the generated code refers to the same location.

■ When a procedure is called,

- it saves, in its own A.R., the current values of all of the variables that it declares itself (i.e., if it declares x and y , then it saves the values of x and y that are currently in the space for x and y).
- It restores those values when it finishes.

■ Comparisons:

- Shallow access allows fast access to non-locals, but there is overhead on procedure entry and exit proportional to the number of local variables.
- Deep access needs to use a symbol table at run time.