### Code Generation

ASU Textbook Chapter 8, Chapter 7.5

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## **Code generation**

- Compiler usually generate intermediate codes.
  - Ease of re-targeting different machines.
  - Perform machine-independent code optimization.
- Intermediate language:
  - Postfix language: stack-based machine-like language.
  - Syntax tree: graphical representation.
  - Three-address code: a statement containing at most 3 addresses or operands.
    - ▶ A sequence of statements of the general form: x := y op z, where "op" is an operator.
    - ▶ A linearized representation of a binary syntax tree.
    - ▶ Consists of at most 3 addresses for each statement.
    - $\triangleright$  x is the result, and y and z are operands.

## Types of three-address statements

#### Assignment

- Binary: x := y op z
- Unary:  $x := \mathbf{op} \ y$
- "op" can be any reasonable arithmetic or logical operator.

### Copy

- Simple: x := y
- Indexed: x := y[i] or x[i] := y
- Address and pointer manipulation:

$$\triangleright x := \& y$$

$$\triangleright x := *y$$

$$\triangleright *x := y$$

#### Jump

- Unconditional: goto L
- Conditional: if x relop y goto  $L_1$  [else goto  $L_2$ , where relop is  $<,=,>,\geq,\leq$  or  $\neq$ .

#### Procedure call

• Call procedure 
$$P(X1, X2, \dots, Xn)$$

PARAM X1

### **Declarations**

- Global data: generate address in the static data area.
- Local data in a procedure or block:
  - Create a symbol table entry with
    - data type;
    - ▶ relative address within the A.R. (offset).
  - Depend on the target machine, determine data alignment.
    - ▶ For example: if a word has 2 bytes and an integer variable is represented with a word, then we may require all integers to start on even addresses.

## Declarations — examples

```
P \rightarrow MD
       • M \rightarrow \epsilon
        \{\text{offset} := 0\}
\blacksquare D \to D; D
\blacksquare D \rightarrow id:T
       • { enter_symbol_table(id.name, T.type, offset);
       offset := offset + T.width }
\blacksquare T \rightarrow integer
       { T.type := integer;
       • T.width := 4 }
\blacksquare T \rightarrow real

    { T.type := real;

       • T.width := 8 }
\blacksquare T \longrightarrow *T_1
       • { T.type := pointer(T_1.type);
       • T.width := 4 }
lacksquare T 	o array [num] 	ext{ of } T_1
       • { T.type := array(num.val,T_1.type);
       • T.width := num.val * T_1.width; }
```

## Symbol table operations

- Treat symbol tables as objects:
  - mktable(previous):
    - ▶ make a new table, offset in the new table is 0,
    - ▶ link it to the previous symbol table, and
    - ▶ make the new table the current working table.
  - deltable(current): return the previous symbol table.
  - enter(table,name,type,offset): insert a new identifier.
  - addwidth(table,width): increase the size of the current A.R. by width.
  - enterproc(table, newtable): create a procedure with its symbol table being "new table."
  - push(object,stack), pop(stack), top(stack): stack-based operations.

# Example for symbol table operations (1/2)

- Keeping track of scope information.
  - When a nested procedure is seen, processing of declarations in the enclosing procedure is temporarily suspended.

```
■ P 	o M_1D

▷ {addwidth(top(tblptr),top(offset));}

▷ pop(tblptr); pop(offset);}

■ M_1 	o \epsilon

▷ {t := mktable(null);

▷ push(t,tblptr); push(0,offset);}

■ D 	o D_1; D_2
```

# Example for symbol table operations (2/2)

```
• D \rightarrow proc\ id; M_2D_1; M_3\ Statements
       \triangleright { t := top(tblptr); /* save symbol table */
       \triangleright addwidth(t,top(offset));
       ▶ generate code for de-allocating A.R.
       pop(tblptr); pop(offset); deltable(tblptr); }
• D \rightarrow id:T
       ▶ {enter(top(tblptr),id.name,T.type,top(offset));
       \triangleright top(offset) := top(offset) + T.width; }
• M_2 \rightarrow \epsilon
       \triangleright t := mktable(top(tblptr));
       \triangleright push(t,tblptr); push(0,offset);
       ▶ enterproc(top(tblptr),t);}
• M_3 \rightarrow \epsilon
       ▶ {generate code for allocating A.R. }
```

## Handling names in records

A record declaration is treated as entering a block in terms of "offset" is concerned.

Example:

```
    T → record Marker D end

            { T.type := record(top(tblptr));
            ▷ T.width := top(offset);
            ▷ pop(tblptr);
            ▷ pop(offset); }

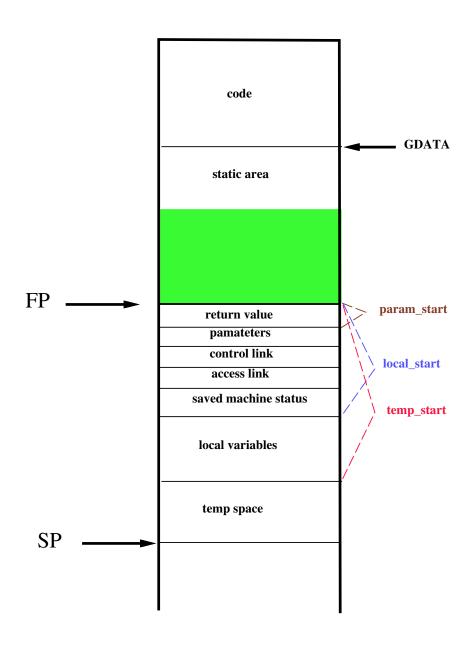
    Marker → ϵ

            { t := mktable(null);
            ▷ push(t.tblptr);
            ▷ push(0,offset);}
```

## **Code generation routines**

- Code generation:
  - emit([address #1], [assignment], [address #2], operator, address #3);
    - ▶ Use switch statement to actually print out the target code;
    - ▶ Can have different emit() for different target codes;
- Variable accessing: depend on type of [address #i], generate different codes.
  - Watch out the differences between l-address and r-address.
  - Local temp space: FP+temp\_start+offset.
  - Parameter: FP+param\_start+offset.
  - Local variable: FP+local\_start+offset.
  - Non-local variable:
    - ▶ trace the access link a suitable number of times to get the FP of the declaring procedure;
    - > then use the formula for local variable.
  - Global variable: GDATA+offset.
  - Registers, constants, . . .

# **Example for memory management**



## Code generation service routines

- Error handling routine: error(error information);
  - Use switch statement to actually print out the error message;
  - The messages can be written and stored in other file.
- Temp space management:
  - This is needed in generating code for expressions.
  - newtemp(): allocate a temp space.
    - ▶ Using a bit array to indicate the usage of temp space.
    - ▶ Usually use a circular array data structure.
  - freetemp(t): free temp space t.
- Label management:
  - This is needed in generated branching statements.
  - newlabel(): generate a label in the target code that has never been used.
- Symbol table lookup:
  - lookup(name,t): check whether name is declared in symbol table t, return the entry if it is in t.

## **Assignment statements**

```
S \rightarrow id := E
      { p := lookup(id.name,symbol_table);
      if p is not null then emit(p, ":=",E.place);
         else error("var undefined",id.name); }
\blacksquare E \rightarrow E_1 + E_2
      • {E.place := newtemp(); freetemp(E_1.place); freetemp(E_2.place);
      • emit(E.place, ":=",E_1.place,"+",E_2.place);}
\blacksquare E \rightarrow E_1 * E_2
      • {E.place := newtemp(); freetemp(E_1.place); freetemp(E_2.place);
      • emit(E.place, ":=",E_1.place,"*",E_2.place);}
\blacksquare E \rightarrow -E_1
      • {E.place := newtemp(); freetemp(E_1.place);
      • emit(E.place, ":=", "uminus",E_1.place); }
\blacksquare E \to (E_1)
      • {E.place := E_1.place;}
\blacksquare E \rightarrow id
      {p := lookup(id.name,symbol_table);

    if p \( \neq \) null then E.place := p else error("var undefined",id.name);}
```

## Type conversions

- Assume there are only two types integer and float.
- $\blacksquare E \rightarrow E_1 + E_2$ 
  - if  $E_1.type == E_2.type$  then
    - generate no conversion code
    - $\triangleright$  E.type =  $E_1$ .type
  - else
    - $\triangleright$  E.type = float
    - $\triangleright temp_1 = newtemp();$
    - ▶ if  $E_1$ .type == integer then emit(temp<sub>1</sub>, ":=", int-to-float, $E_1$ .place); emit(E, ":=",temp<sub>1</sub>, "+", $E_2$ .place);
    - ightharpoonup else emit(temp<sub>1</sub>, ":=", int-to-float,  $E_2$ .place); emit(E, ":=", temp<sub>1</sub>, "+",  $E_1$ .place);
    - ightharpoonup freetemp(temp<sub>1</sub>);

## Addressing 1-D array elements

- 1-D array: A[i].
  - Assumptions:
    - $\triangleright$  lower bound in address = low
    - $\triangleright$  element data width = w
    - $\triangleright$  starting address =  $start\_addr$
  - Address for A[i]
    - $\triangleright = start\_addr + (i low) * w$
    - $\triangleright = i * w + (start\_addr low * w)$
    - ightharpoonup The value of  $(start\_addr low * w)$  can be computed at compile time.

#### PASCAL use

```
array [-8 .. 100] of integer
```

to declare an integer array in the range of [-8], [-7], [-6], ..., [-1], [0], [1], ..., [100].

## Addressing 2-D array elements

- **2-D** array  $A[i_1, i_2]$ .
  - Row major: the preferred mapping method.
    - $\triangleright$  A[1,1], A[1,2], A[1,3], A[2,1], A[2,2], ...
    - ightharpoonup Advantage: A[i,j] = A[i][j].
    - $\triangleright$  A[1] means the first row.
  - Column major:
    - $\triangleright$  A[1,1], A[2,1], A[1,2], A[2,2], A[1,3], ...
- Address for  $A[i_1, i_2]$ 
  - $\bullet = start\_addr + ((i_1 low_1) * n_2 + (i_2 low_2)) * w$
  - $\bullet = (i_1 * n_2 + i_2) * w + (start\_addr low_1 * n_2 * w low_2 * w)$ 
    - $\triangleright$   $n_2$  is the number of elements in a row.
    - $\triangleright$  low<sub>1</sub> is the lower bound of the first coordinate.
    - $\triangleright$  low<sub>2</sub> is the lower bound of the second coordinate.
  - The value  $(start\_addr low_1 * n_2 * w low_2 * w)$  can be computed at compiler time.

## Addressing multi-D array elements

- Similar method for multi-dimensional arrays.
- Address for  $A[i_1, i_2, \ldots, i_k]$ 
  - =  $(i_1 * \prod_{i=2}^k n_i + i_2 * \prod_{i=3}^k n_i + \dots + i_k) * w + (start\_addr low_1 * w * \prod_{i=2}^k n_i low_2 * w * \prod_{i=3}^k n_i \dots low_k * w)$ 
    - $\triangleright$   $n_i$  is the number of elements in the *i*th coordinate.
    - $ightharpoonup low_i$  is the lower of the *i*th coordinate.
  - The value  $(i_1*\Pi_{i=2}^k n_i + i_2*\Pi_{i=3}^k n_i + \cdots + i_k)$  can be computed incrementally in grammar rules.
    - $ightharpoonup f(1) = i_1;$
    - $ightharpoonup f(j) = f(j-1) * n_j + i_j;$
    - $\triangleright$  f(k) is the value we want;
  - The value  $(start\_addr-low_1*w*\Pi_{i=2}^kn_i-low_2*w*\Pi_{i=3}^kn_i-\cdots-low_k*w)$  can be computed at compile time.
    - ▶ Let base =  $(start\_addr low_1 * w * \Pi_{i=2}^k n_i low_2 * w * \Pi_{i=3}^k n_i \cdots low_k * w)$ .

## Code generation for arrays

```
lacksquare L 	o Elist

ightharpoonup {L.offset := newtemp(); freetemp(Elist.place);
       ▶ emit(L.offset, ":=",Elist.elesize, "*",Elist.place);
       ▶ emit(L.offset, ":=",L.offset, "+",Elist.base);}
\blacksquare Elist \rightarrow Elist_1, E
       \triangleright { t := newtemp(); m := Elist_1.ndim + 1;
       \triangleright emit(t, ":=", EList_1.place, "*", limit(Elist_1.array,m));
       \triangleright emit(t, ":=",t,"+",E.place); freetemp(E.place);
       \triangleright Elist.array := Elist_1.array; Elist.place := t; EList.ndim := m; }
\blacksquare Elist \rightarrow id \ [E]

ightharpoonup { Elist.place := E.place; Elist.ndim := 1;
       ▷ p := lookup(id.name,symbol_table); check for id errors;
       ▶ Elist.elesize := p.size; Elist.base := p.base;
       ▶ EList.array := p.place;}
\blacksquare E \rightarrow id
       ▶ {p := lookup(id.name,symbol_table); check for id errors;
       \triangleright E.place := p.place;
```

## **Boolean expressions**

- Two choices for implementation:
  - Numerical representation: encode true and false values numerically, evaluate analogously to an arithmetic expression.

```
    ▶ 1: true; 0: false.
    ▶ ≠ 0: true; 0: false.
```

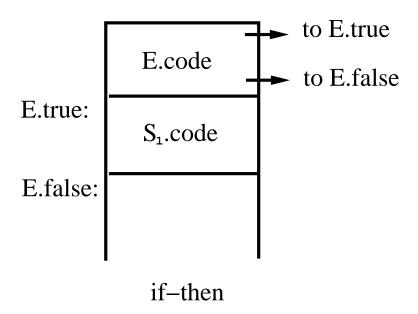
- Flow of control: representing the value of a boolean expression by a position reached in a program.
- Short-circuit code.
  - Generate the code to evaluate a boolean expression in such a way that it is not necessary for the code to evaluate the entire expression.
  - if  $a_1$  or  $a_2$   $a_1$  is true, then  $a_2$  is not evaluated.
  - Similarly for "and".
  - Side effects in the short-circuited code are not carried out.

## **Numerical representation**

```
\blacksquare E \rightarrow id_1 \ relop \ id_2
    {E.place := newtemp();
    • emit("if", id_1.place,relop.op, id_2.place, "goto",nextstat+3);
    emit(E.place, ":=", "0");
    emit("goto",nextstat+2);
    emit(E.place, ":=", "1");}
Example for translating (a < b or c < d and e < f):
 100: if a < b goto 103
                             107: t2 := 1
 101: t1 := 0
                              108: if e < f goto 111
 102: goto 104
                              109: t3 := 0
 103: t1 := 1 /* true */ 110: goto 112
 105: t2 := 0 /* false */ 112: t4 := t2 and t3
 106: goto 108
                              113: t3 := t1 or t4
```

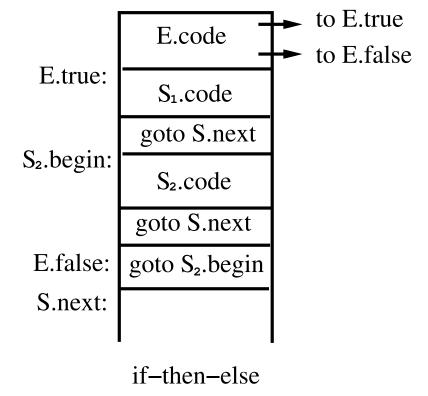
## Flow of control representation

```
 E \rightarrow id_1 \ relop \ id_2 
 \bullet \  \{ \  \, \text{E.true} := \text{newlabel();} \\
 \bullet \  \, \text{E.false} := \text{newlabel();} \\
 \bullet \  \, \text{emit("if"}, id_1, \text{relop}, id_2, \text{"goto", E.true, "else", "goto", E.false);} \\
 \bullet \  \, \text{emit(E.true, ":");} 
 \bullet \  \, S \rightarrow \  \, \text{if} \  \, E \  \, \text{then} \  \, S_1 \\
 \bullet \  \, \text{emit(E.false, ":");}
```



### If-then-else

```
\blacksquare E \rightarrow id_1 \ relop \ id_2
       { E.true := newlabel();
       E.false := newlabel();
       • emit("if",id_1,relop,id_2, "goto",
          E.true, "else", "goto", E.false);
       emit(E.true, ":");}
lacksquare S 
ightarrow \ 	ext{if} \ E \ 	ext{then} \ S_1 \ M_3 \ 	ext{else} \ M_4 \ S_2
       • {S.next = M_3.next;
       emit("goto",S.next);
       emit(E.false, ":");
       • emit("goto",M_4.label);
       emit(S.next, ":");}
\blacksquare M_3 \to \epsilon
       • \{M_3.\mathsf{next} := \mathsf{newlabel()};
       • emit("goto", M<sub>3</sub>.next);}
M_4 \rightarrow \epsilon
       • \{M_4.label := newlabel();
       • emit(M<sub>4</sub>.label, ":");}
```



## While loop

S.begin:

- $E oup id_1 \ relop \ id_2$  { E.true := newlabel();

   E.false := newlabel();

   emit("if",  $id_1$ , relop,  $id_2$ , "goto",

  E.true, "else", "goto", E.false);

   emit(E.true, ":");}

   S oupwhile  $M_5 \ E \ do \ S_1$  {S.begin =  $M_5$ .begin;

   emit("goto", S.begin);

   emit(E.false, ":");}
- E.true:

  S<sub>1</sub>.code

  goto S.begin

  E.false:

  while loop

E.code

to E.true

•  $M_5 \rightarrow \epsilon$ •  $\{M_5.\mathsf{begin} := \mathsf{newlabel()};$ •  $\mathsf{emit}(M_5.\mathsf{begin}, ":");\}$ 

# Case/Switch statement

#### C-like syntax:

```
switch expr{
case V<sub>1</sub>: S<sub>1</sub>
...
case V<sub>k</sub>: S<sub>k</sub>
default: S<sub>d</sub>
}
```

### Translation sequence:

- Evaluate the expression.
- Find which value in the list matches the value of the expression, match default only if there is no match,
- Execute the statement associated with the matched value.

#### How to find the matched value:

- Sequential test.
- Look-up table.
- Hash table.
- Back-patching.

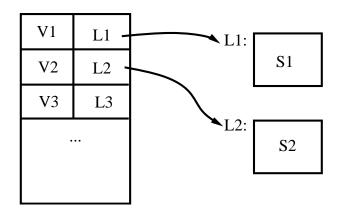
# Implementation of case statements (1/2)

Two different translation schemes for sequential test.

```
code to evaluate E into t
goto test
L1: code for S1
                                                   code to evaluate E into t
    goto next
                                                   if t <> V1 goto L1
                                                   code for S1
Lk: code for Sk
                                                  goto next
    goto next
                                              L1: if t <> V2 goto L2
Ld: code for Sd
                                                   code for S2
    goto next
                                                  goto next
test:
    if t = V1 goto L1
                                              L(k-1): if t <> Vk goto Lk
                                                   code for Sk
    . . .
    if t = Vk goto Lk
                                                  goto next
    goto Ld
                                              Lk: code for Sd
next:
                                              next:
Can easily be converted into a lookup table!
```

# Implementation of case statements (2/2)

Use a table and a loop to find the address to jump.



- Hash table: when there are more than 10 entries, use a hash table to find the correct table entry.
- Back-patching:
  - Generate a series of branching statements with the targets of the jumps temporarily left unspecified.
  - To-be-determined label table: each entry contains a list of places that need to be back-patched.
  - Can also be used to implement labels and goto's.

### **Procedure calls**

- Space must be allocated for the A.R. of the called procedure.
- Arguments are evaluated and made available to the called procedure in a known place.
- Save current machine status.
- When a procedure returns
  - place return value in a known place
  - restore A.R.

## **Example for procedure call**

#### Example:

```
• S \rightarrow \operatorname{call} id(Elist)

• {for each item p on the queue Elist.queue do

• \operatorname{emit}("PARAM", q);

• \operatorname{emit}("call", id.place);}

• Elist \rightarrow Elist, E

• {append E.place to the end of Elist.queue}

• Elist \rightarrow E

• {initialize Elist.queue to contain only E.place}
```

#### Idea:

- Use a queue to hold parameters, then generate codes for parameters.
- May have code like:

```
ightharpoonup code for <math>E_1, store in t_1

ightharpoonup code for <math>E_k, store in t_k

ightharpoonup PARAM t_1

ightharpoonup PARAM t_k

ightharpoonup call p
```

## Parameter passing

- Terminology:
  - procedure declaration:
    - > parameters, formal parameters, or formals.
  - procedure call:
    - > arguments, actual parameters, or actuals.
- The value of a variable:
  - r-value: the current value of the variable.
    - > right value
    - ▶ on the right side of assignment
  - l-value: the location/address of the variable.
    - ▶ left value
    - ▶ on the left side of assignment
  - Example: x := y
- Four different modes for parameter passing
  - call-by-value
  - call-by-reference
  - call-by-value result (copy-restore)
  - call-by-name

## Call-by-value

Usage:

- Used by PASCAL if you use non-var parameters.
- Used by C++ if you use non-& parameters.
- The only thing used in C.
- Idea:
  - calling procedure copies the r-values of the arguments into the called procedure's A.R.
- Effect:
  - Changing a formal parameter (in the called procedure) has no effect on the corresponding actual. However, if the formal is a pointer, then changing the thing pointed to does have an effect that can be seen in the calling procedure.

void f(int \*p)
{ \*p = 5;
 p = NULL;
}

main()
{int \*q = malloc(sizeof(int));
\*q=0;
f(q);

- In main, q will not be affected by the call of f.
- That is, it will not be NULL after the call.
- However, the value pointed to by q will be changed from 0 to 5.

# Call-by-reference (1/2)

#### Usage:

- Used by PASCAL for var parameters.
- Used by C++ if you use & parameters.
- FORTRAN.

#### Idea:

- Calling procedure copies the l-values of the arguments into the called procedure's A.R. as follows:
  - ▶ If an argument has an address then that is what is passed.
  - ▶ If an argument is an expression that does not have an l-value (e.g., a+6), then evaluate the argument and store the value in a temporary address and pass that address.

#### Effect:

- Changing a formal parameter (in the called procedure) does affect the corresponding actual.
- Side effects.

# Call-by-reference (2/2)

```
FORTAN quirk (using C++ syntax)
void mistake(int & x)
{x = x+1;}

Example: main()
{mistake(1);
cout<<1;
}
```

- In C++, you get a warning from the compiler because x is a reference parameter that is modified, and the corresponding actual parameter is a literal.
- The output of the program is 1.
- However, in FORTRAN, you would get no warning, and the output may be 2. This happens when FORTRAN compiler stores 1 as a constant at some address and uses that address for all the literal "1" in the program.
- In particular, that address is passed when "mistake()" is called, and is also used to fetch the value to be written by "count". Since "mistake()" increases its parameter by 1, that address holds the value 2 when it is executed.

## Call-by-value-result

- Usage: FORTRAN IV and ADA.
- Idea:
  - Value, not address, is passed into called procedure's A.R.
  - When called procedure ends, the final value is copied back into the argument's address.
- Equivalent to call-by-reference except when there is aliasing.
  - "Equivalent" in the sense the program produces the same results, NOT the same code will be generated.
  - Aliasing: two expressions that have the same l-value are called aliases. That is, they access the same location from different places.
  - Aliasing happens through pointer manipulation.
    - ▶ call-by-reference with an argument that can also be accessed by the called procedure directly, e.g., global variables.
    - $\triangleright$  call-by-reference with the same expression as an argument twice; e.g., test(x, y, x).

# Call-by-name (1/2)

- Usage: Algol.
- Idea: (not the way it is actually implemented.)
  - Procedure body is substituted for the call in the calling procedure.
  - Each occurrence of a parameter in the called procedure is replaced with the corresponding argument, i.e., the TEXT of the parameter, not its value.
  - Similar to macro substitution.

# Call-by-name (2/2)

Conceptual result of substitution:

Call-by-name is not really implemented like macro expansion.
 Recursion would be impossible, for example, using this approach.

## How to implement call-by-name?

- Instead of passing values or addresses as arguments, a function (or the address of a function) is passed for each argument.
- These functions are called thunks. , i.e., a small piece of code.
- Each thunk knows how to determine the address of the corresponding argument.
  - Thunk for j: find address of j.
  - Thunk for A[j]: evaluate j and index into the array A; find the address of the appropriate cell.
- Each time a parameter is used, the thunk is called, then the address returned by the thunk is used.
  - y = 0: use return value of thunk for y as the l-value.
  - x=x+1: use return value of thunk for x both as l-value and to get r-value.
  - For the example above, call-by-reference executes A[1]=0 ten times, while call-by-name initializes the whole array.
- Note: call-by-name is generally considered a bad idea, because it is hard to know what a function is doing — it may require looking at all calls to figure this out.

## Advantages of call-by-value

- Consider not passing pointers.
- No aliasing.
- Arguments unchanged by procedure call.
- Easier for static optimization analysis for both programmers and the complier.
- Example:

```
x = 0;
Y(x); /* call-by-value */
z = x+1; /* can be replaced by z=1 for optimization */
```

 Compared with call-by-reference, code in the called function is faster because no need for redirecting pointers.

# Advantages of call-by-reference

- Efficiency in passing large objects.
- Only need to copy addresses.

## Advantages of call-by-value-result

- More efficient than call-by-value for small objects.
- If there is no aliasing, we can implement call-by-value-result using call-by-reference for large objects.

## Advantages of call-by-name

- More efficient when passing parameters that are never used.
- Example:

```
P(Ackerman(5),0,3)
/* Ackerman's function takes enormous time to compute */
function P(int a, int b, int c)
{ if(odd(c)){
    return(a)
    }else{ return(b) }
}
```

- Note: if the condition is false, then, using call-by-name, it is never necessary to evaluate the first actual at all.
- ullet This saves lots of time because evaluating a takes a long time.