

Theory of Computer Games: Selected Advanced Topics

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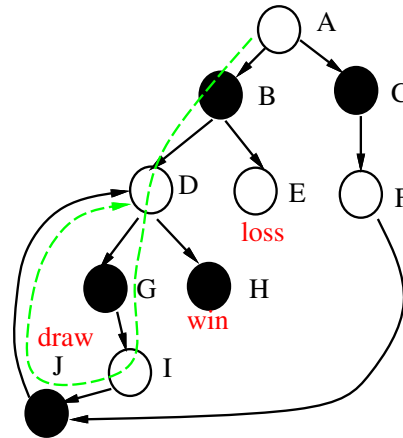
Abstract

- **Some advanced research issues.**
 - The graph history interaction (GHI) problem.
 - Opponent models.
 - Multi-player game tree search.
 - Bit board speedup.
 - Proof-number search.
- **More research topics.**
 - The influence of rules on games.
 - ▷ *Allowing long cycles in Go.*
 - ▷ *The scoring of a suicide ply in chess.*
 - Why a position is difficult to human?
 - Unique features in games.

Graph history interaction problem

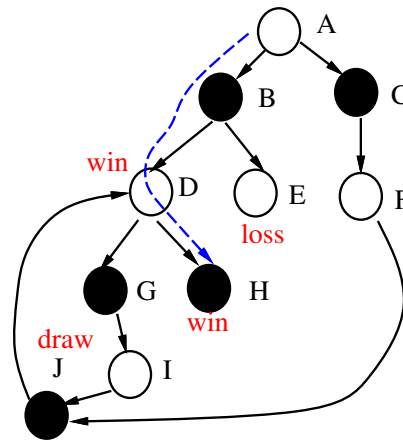
- The graph history interaction (**GHI**) problem [Campbell 1985]:
 - In a game graph, a position can be visited by more than one paths from a starting position.
 - The value of the position depends on **the path** visiting it.
 - ▷ *It can be win, loss or draw for Chinese chess.*
 - ▷ *It can only be draw for Western chess and Chinese dark chess.*
 - ▷ *It can only be loss for Go.*
- In the transposition table, you record the value of a position, but not the path leading to it.
 - Values computed from rules on repetition cannot be used later on.
 - It takes a huge amount of storage to store all the paths visiting it.
- This is a very difficult problem to be solved in real time [Wu et al '05] [Kishimoto and Müller '04].

GHI: when loop draws



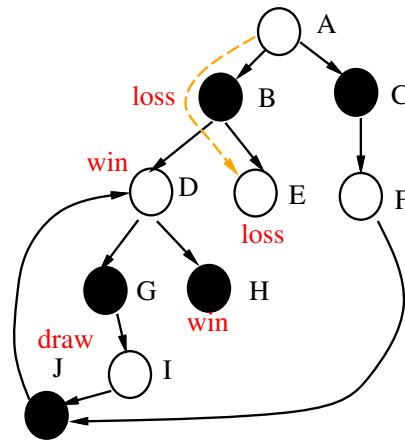
- Assume if the game falls into a loop, then it is a draw.
- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow I \rightarrow J \rightarrow D$ is draw by **rules of repetition**.
 - ▷ *Memorized J as a draw position.*

GHI: when loop draws



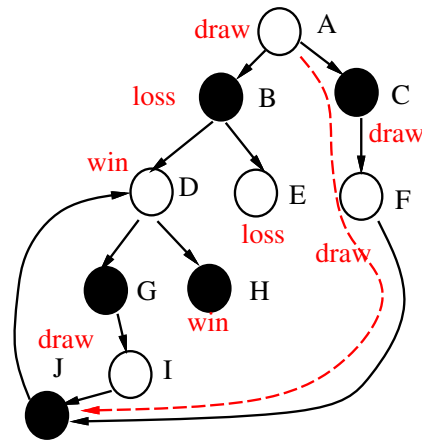
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- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow I \rightarrow J \rightarrow D$ is draw by **rules of repetition**.
 - ▷ *Memorized J as a draw position.*
- $A \rightarrow B \rightarrow D \rightarrow H$ is a win. Hence D is win.

GHI: when loop draws



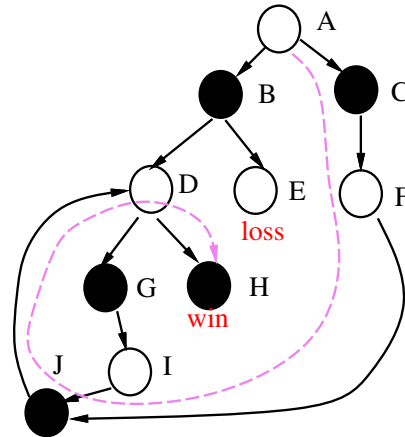
- Assume if the game falls into a loop, then it is a draw.
- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow I \rightarrow J \rightarrow D$ is draw by **rules of repetition**.
 - ▷ Memorized J as a draw position.
- $A \rightarrow B \rightarrow D \rightarrow H$ is a win. Hence D is win.
- $A \rightarrow B \rightarrow E$ is a loss. Hence B is loss.

GHI: when loop draws



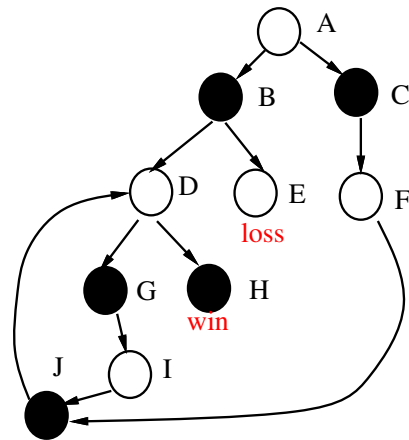
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- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow I \rightarrow J \rightarrow D$ is draw by **rules of repetition**.
 - ▷ *Memorized J as a draw position.*
- $A \rightarrow B \rightarrow D \rightarrow H$ is a win. Hence D is win.
- $A \rightarrow B \rightarrow E$ is a loss. Hence B is loss.
- $A \rightarrow C \rightarrow F \rightarrow J$ is draw because J is recorded as draw.
- A is draw because one child is loss and the other child is draw.

GHI: when loop draws



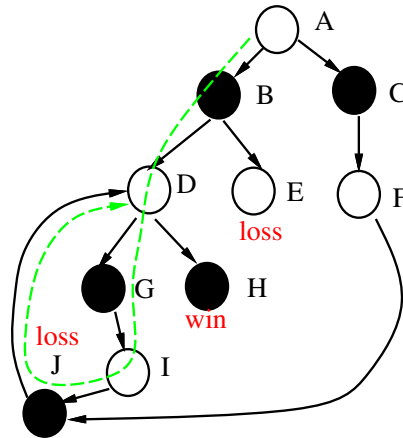
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- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow I \rightarrow J \rightarrow D$ is draw by **rules of repetition**.
 - ▷ *Memorized J as a draw position.*
- $A \rightarrow B \rightarrow D \rightarrow H$ is a win. Hence D is win.
- $A \rightarrow B \rightarrow E$ is a loss. Hence B is loss.
- $A \rightarrow C \rightarrow F \rightarrow J$ is draw because J is recorded as draw.
- A is draw because one child is loss and the other child is draw.
- However, $A \rightarrow C \rightarrow F \rightarrow J \rightarrow D \rightarrow H$ is a win (for the root).

GHI: when loop wins



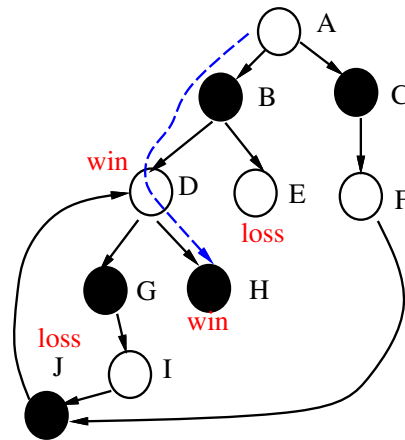
- Assume the one causes loops wins the game.

GHI: when loop wins



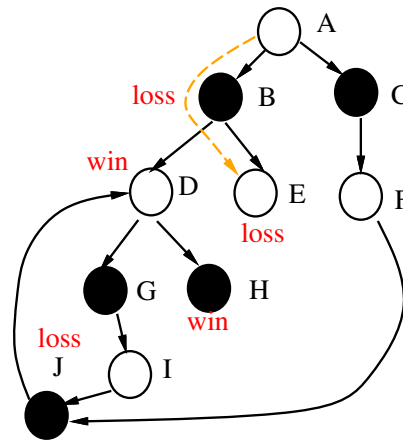
- **Assume the one causes loops wins the game.**
- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow I \rightarrow J \rightarrow D$ is **loss** because of **rules of repetition**.
 - ▷ *Memorized J as a loss position (for the root).*

GHI: when loop wins



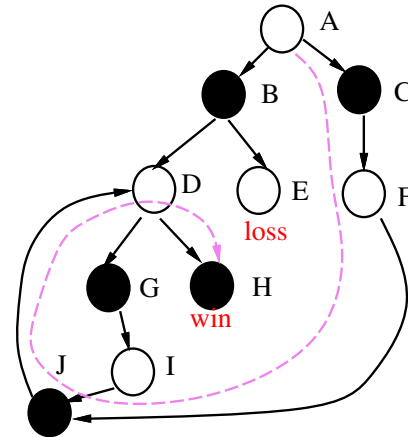
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 - ▷ *Memorized J as a loss position (for the root).*
- $A \rightarrow B \rightarrow D \rightarrow H$ is a **win**. Hence D is win.

GHI: when loop wins



- **Assume the one causes loops wins the game.**
- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow I \rightarrow J \rightarrow D$ is **loss** because of **rules of repetition**.
 - ▷ *Memorized J as a loss position (for the root).*
- $A \rightarrow B \rightarrow D \rightarrow H$ is a **win**. Hence D is win.
- $A \rightarrow B \rightarrow E$ is a **loss**. Hence B is loss.

GHI: when loop wins



- **Assume the one causes loops wins the game.**
- $A \rightarrow B \rightarrow D \rightarrow G \rightarrow I \rightarrow J \rightarrow D$ is loss because of **rules of repetition**.
 - ▷ *Memorized J as a loss position (for the root).*
- $A \rightarrow B \rightarrow D \rightarrow H$ is a win. Hence D is win.
- $A \rightarrow B \rightarrow E$ is a loss. Hence B is loss.
- $A \rightarrow C \rightarrow F \rightarrow J$ is loss because J is recorded as loss.
- A is loss because both branches lead to loss.
- **However, $A \rightarrow C \rightarrow F \rightarrow J \rightarrow D \rightarrow H$ is a win (for the root).**

Comments

- Using DFS to search the above game graph from left first or from right first produces two different results.
- Position A is actually a win position.
 - Problem: memorize J being draw is only valid when the path leading to it causes a loop.
- Storing the path leading to a position in a transposition table requires too much memory.
 - Maybe we can store some forms of hash code to verify it.
- Finding a better data structure for solving this problem remains to be a challenging research issue.

Opponent models

- In a normal alpha-beta search, it is assumed that you and the opponent use the same strategy.
 - What is good to you is bad to the opponent and vice versa!
 - Hence we can reduce a minimax search to a NegaMax search.
 - This is normally true when the game ends, but may not be true in the middle of the game.
- What will happen when there are two strategies or evaluation functions f_1 and f_2 so that
 - for some positions p , $f_1(p)$ is **better** than $f_2(p)$
 - ▷ “better” means closer to the real value $f(p)$
 - for some positions q , $f_2(q)$ is **better** than $f_1(q)$
- If you are using f_1 and you know your opponent is using f_2 , what can be done to take advantage of this information.
 - This is called OM (**opponent model**) search [Carmel and Markovitch 1996].
 - ▷ In a MAX node, use f_1 .
 - ▷ In a MIN node, use f_2 .

Other usage of the opponent model

- Depend on strength of your opponent, decide whether to force an easy draw or not.
 - This is called the **contempt factor**.
- Example in CDC:
 - It is easy to chase the king of your opponent using your pawn.
 - Drawing a weaker opponent is a waste.
 - Drawing a stronger opponent is a gain.
- It is feasible to use a learning model to “guess” the level of your opponent as the game goes and then adapt to its model in CDC [Chang et al 2021].

Opponent models – comments

■ Comments:

- Need to know your opponent's model precisely or to have some knowledge about your opponent.
- How to learn the opponent model on-line or off-line?
- When there are more than 2 possible opponent strategies, use a probability model (PrOM search) to form a strategy.

■ Remark: A common misconception is if your opponent uses a worse strategy f_3 than the one, namely f_2 , used in your model, then he may get advantage.

- **This is impossible** if f_2 is truly better than f_3 .
- If f_1 can beat f_2 , then f_1 can sure beat f_3 .

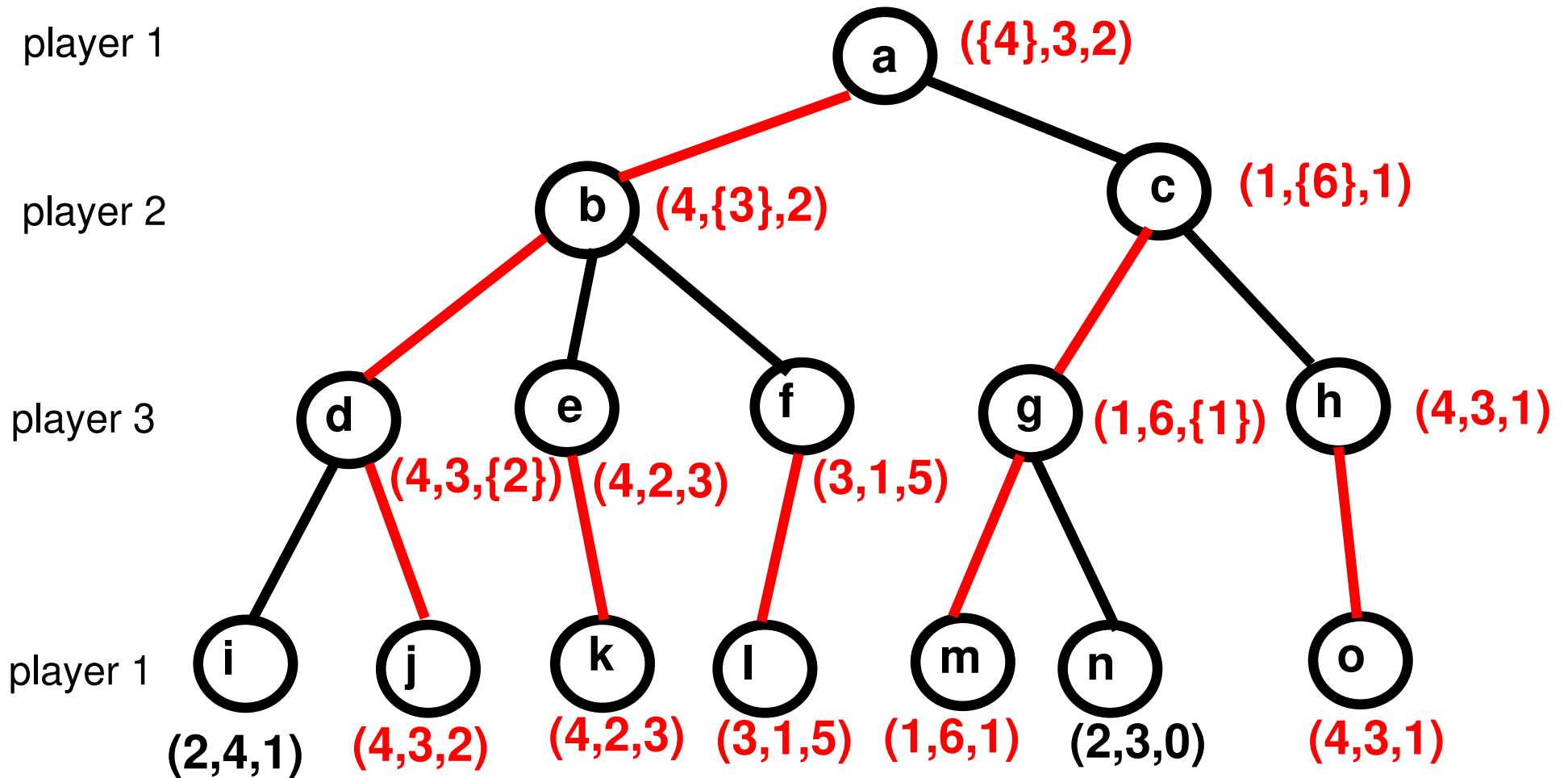
Multi-player game tree search

- Games with more than 2 players.
 - Mahjong: 4 players
 - Contract bridge or bridge: 4 players
 - Monopoly: 2 to many players
 - Scrabble: 2 to 4 players
 - Risk: 2 to 6 players
- Assume we have n players, y_1, \dots, y_n in a game.
 - We have n evaluating functions, $score_i$, one for each player.
 - Given a position p with the children p_1, \dots, p_m , let $score_i(p)$ be the score of y_i for p .
 - ▷ If p is a terminal position for y_i , then $m = 0$ and $score_i(p)$ is the “true” score of y_i in p .
 - ▷ Otherwise, $score_i(p) = \max_{j=1}^m score_i(p_j)$.
 - The above algorithm is called MAX^n where stands for during each turn, each player maximizes his own score without considering scores of others.

MAXⁿ: algorithm

- $next_player(idx)$: the player who is next to player idx .
- Brute force algorithm for multi-player games.
- Algorithm MAXN(position p , player idx)
 - output: $best$ which is an array with $best[i]$ being the best value for player i so far.
 - If p is terminal, then return $best[i] = score_i(p), \forall i$;
 - initialize $best$ to be $best[i] = -\infty, \forall i$;
 - Let p_i be the i th child of p ;
 - for $i = 1$ to last child of p do
 - ▷ $current = MAXN(p_i, next_player(idx))$;
 - ▷ if $current[idx] > best[idx]$, $best = current$; // maximized player idx
 - return $best$;

MAXⁿ: example ($n = 3$)



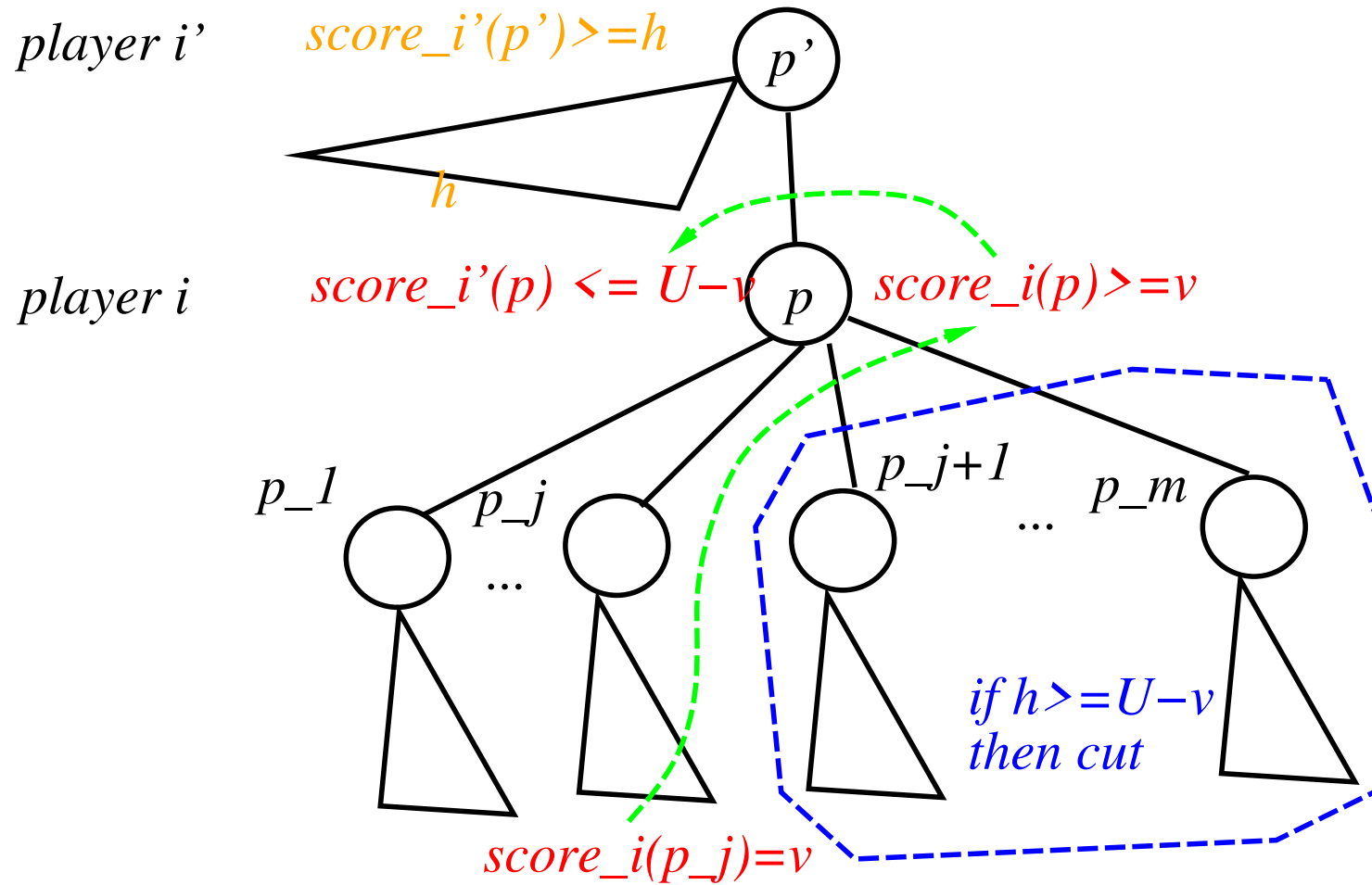
Opportunities for pruning

- Let p be a position in a multi-player game.
- Alpha-beta pruning is a special case for $n = 2$ and cannot be generalized for $n > 2$.
 - Property used in alpha-beta pruning:
 - ▷ *Zero sum: for a position p , $score_1(p) + score_2(p) = 0$.*
 - ▷ *What is good for y_1 is definitely bad for y_2 .*
 - The above may not be true for $n > 2$.
- For a position p , if there is no constraints on the n scores of p , then it is impossible to have any cut offs for MAX^n .
 - In applications we often have the following properties.
 - ▷ *The sum of all n scores for p has an upper bound U .*
 - ▷ *The score of p for any player has a lower bound L .*
 - Examples:
 - ▷ *Go for n players: each player owns pieces of a distinct color.*
→ *the sum of all points \leq the board size, and the score cannot be negative.*
 - ▷ *Othello for n players: each player owns pieces of a distinct color and flips all pieces of different colors.*
→ *the sum of all points \leq the plys played so far and the score cannot be negative.*

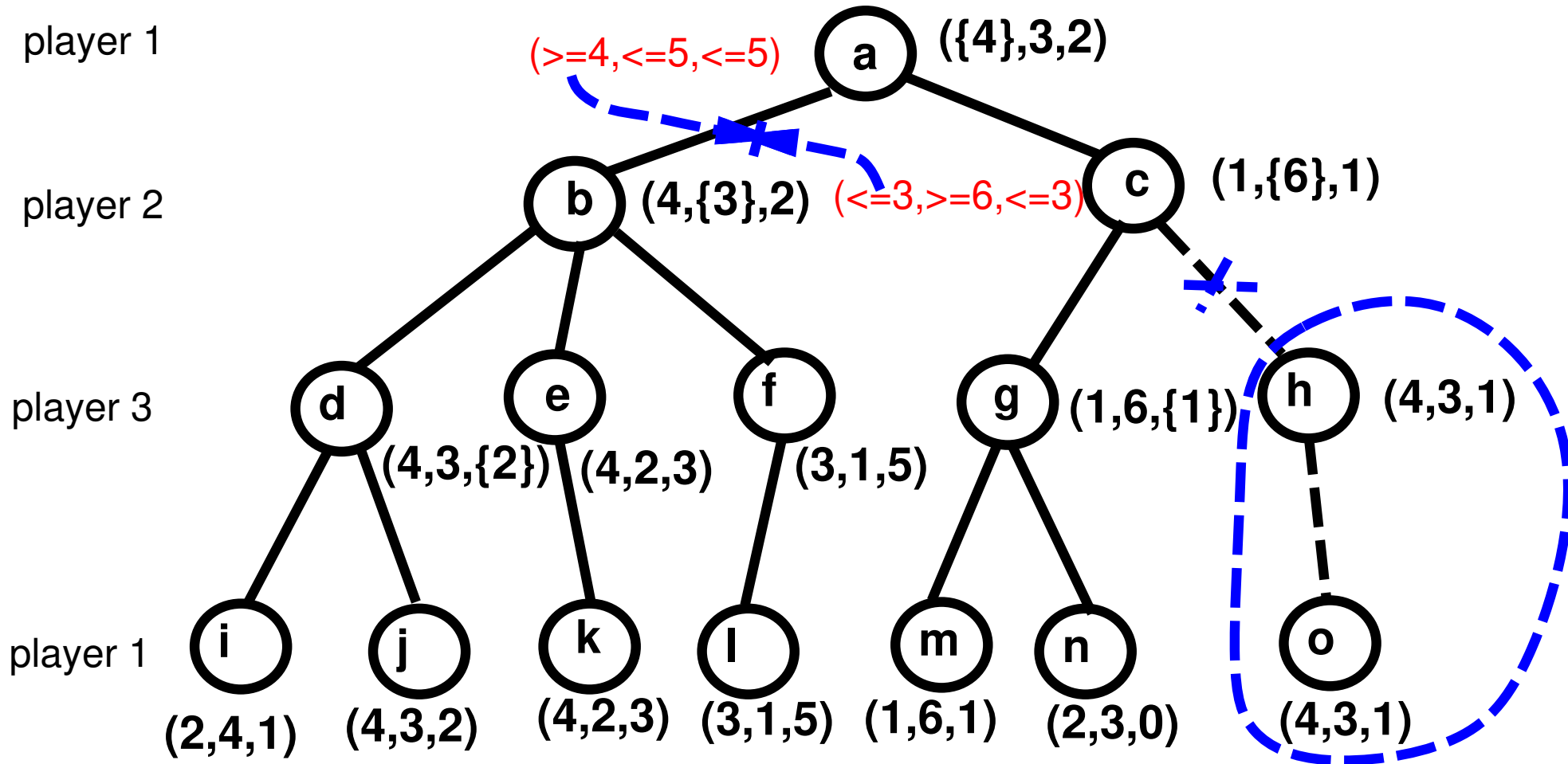
Pruning

- **Recall:** a position p with the children p_1, \dots, p_m and the parent p' , and $score_i(p)$ is the score of player i for p .
- **Direct pruning:**
 - During the turn of the i th player, if $score_i(p_j) = U$, then no more search is needed.
- **Shallow pruning:**
 - Without loss of generality, assume $L = 0$.
 - During the turn of the i th player, if $score_i(p_j) = v$ so far, then $score_i(p) \geq v$ since each player is a max player.
 - This implies $score_j(p) \leq U - v$ if $j \neq i$.
 - Let i' be the index of the immediate previous player.
 - We know $score_{i'}(p') \geq h$ if he has done some searching.
 - If $h \geq U - v$, then we have a cut off.

MAXⁿ: ideas



MAXⁿ: cutoff example ($n = 3, U = 9$)



Remarks about pruning in MAX^n

- Direct pruning is a degenerated case of the shallow pruning by the following settings.
 - If $v = U$, then the scores of all other players are all zero.
 - Using the lower bound L , you can get a cut off.
- Compared to two-player alpha-beta pruning, both direct and shallow prunnings can be used in $n \geq 2$.
- Deep pruning does not work when $n > 2$.
 - Assume you are searching the node w , v is your parent and u is an ancestor that is not v .
 - Assume node x is the turn of player $player(x)$.
 - Any value of $score_{player(u)}(u)$ cannot produce any cutoff on searching the tree T_w because $player(v)$ makes the decision first in propagating the values up.
 - Any value of $score_{player(u)}(w)$ can be propagated up and be used by u .

Algorithm for shallow cut off

■ Functions and data structures

- $next_player(idx)$: the player who is next to player idx .
- $score_i(p)$: the score of player i for the position p .
- U : the upper bound of sum of all scores among all players on a position.
- Assume L is 0.
- $best$ and $current$ are both arrays of size n .

■ Algorithm shallow(position p , player idx , value $bound$)

- return value: $best$ which is an array with $best[i]$ being the best value for player i so far.
- If p is terminal, then return $best[i] = score_i(p), \forall i$;
- Let p_i be the i th child of p ;
- $best = shallow(p_1, next(idx), U)$; // recursive call on the first child
- for $i = 2$ to last child of p do
 - 4.1: if $best[idx] = U$, then return $best$ // immediate cut off
 - 4.2: if $best[idx] \geq bound$, then return $best$ // shallow cut off
 - 4.3: $current = shallow(p_i, next_player(idx), U - best[idx])$;
 - 4.4: if $current[idx] > best[idx]$, $best = current$; // maximize player idx
- return $best$;

Comments

- An generalization for alpha-beta cutoff on adjacent depths.
- Does not work on deep alpha-beta cutoff [Korf 1991].
- In the **best case**, the effective branching factor is $\frac{1+\sqrt{4b-3}}{2}$ where b is the average branching factor.
 - Comparing to alpha-beta cut off, the best effective branching factor is \sqrt{b} .
- In the average case, the effective branching factor is approaching $O(b)$.
 - Comparing to alpha-beta cut off, the the average effective branching factor is $b^{0.75}$ [Fuller et al 1975].
 - This implies most of the cut off come from deep pruning in the average case..
- More research are needed to get more cutoff by observing additional constraints on the values from the application domain.
- MCTS can be easily extended to work on any number of players, but need to work on better properties of convergence.

Hardware Speedup

- **Using hardware to speed up searching is not new.**
 - **Parallel computing.**
 - ▷ *The Northwestern University CHESS program series on the 1970's makes full usage of hardware advantages from supercomputers [Atkin & Slate 1977].*
 - **Special hardware acceleration:**
 - ▷ *Belle: a chess machine with special micro instructions for move generation, alpha-beta pruning and transposition table operations [Condon & Thompson 1982].*
 - ▷ *Deep Blue: custom VLSI FPGA chips for operating chess playing expert systems [Hsu et al 1995].*
- **The above were very costed.**

Bit board techniques

- Everyone can make use of the benefits of hardware acceleration now by smart usage of fast parallel bitwise operations provided by modern day CPU's.
 - Intel CPU's: MMX and SSE [Intel 2021]
 - AMD: 3D Now! [AMD 2000]
- Main technique
 - Using bits to represent the board and pieces on the board.
 - ▷ *Transfer a board into an $n \times m$ picture*
 - ▷ *Transfer pieces into patterns of pixel rectangles*
 - These instructions are usually in the form of SIMD (single instruction multiple data).
 - Many are for image related operations.
 - May also make use of GPU.

Special instruction sets (1/2)

- **Make use of fast parallel bitwise operations provided by modern day CPU's.**
- **Many different types**
 - Find aggregated information
 - Parallel bit deposit and extract
 - ...
- **Most of the instructions can be done using AND, OR, NOT operations, but can be done much faster using special CPU instructions.**

Special instruction sets (2/2)

- Find aggregated information:
 - population count (POPCNT): the number of 1-bits in a “word”.
 - leading/trailing zero count: LZCNT, TZCNT
- Parallel bit deposit and extract
 - Pack in sequence selected bits (PEXT): extract something out
 - ▷ *PEXT(W, Mask)* returns a word by packing to the right those bits in the word *W* whose corresponding bits in the word *Mask* are equal to 1.
 - ▷ *Example: PEXT(010110010, 010101010)* extracts the four even numbered bit and then pack it to the right. Thus it returns 01100.
 - Distribute bits in sequence to selected locations (PDEP): deposit something into.
 - ▷ *PDEP(W, Mask)* returns a word by sending the *i*th bit in the word *W* to the location addressed by the *i*th 1.
 - ▷ *Example: PEXT(01100, 010101010)* deposits the four bits to the even numbered location. Thus it returns 010100000.

Example I

- In Go, how to find the number of empty intersections on the board?
 - Assume you have a long hardware word W of $19*2=38$ bits.
 - ▷ Use 19 words W_1, \dots, W_{19} to represent the rows.
 - Encoding: bits i and $i+1$ in W_j represents the status of the intersection at the i th column and j th row.
 - ▷ 00 means empty.
 - ▷ 10 means a black stone.
 - ▷ 01 means a white stone.
 - $\text{POPCOUNT}(W_j)$ gives the number of stones in the j th row.
 - $19\text{-POPCOUNT}(W_j)$ gives the number of empty intersections in the j th row.

Example II

- In Chinese Dark Chess (CDC), how to find all pieces of a color on the board?
 - Assume you have a long hardware word W of $32 \times 3 = 96$ bits.
 - Encoding: bits $3i$, $3i + 1$, and $3i + 2$ in W_b represents the status of the i th cell on the board with regard to black. Similarly, we have W_R for the red side.
 - ▷ 000 means empty, or pieces of other color or dark.
 - ▷ xyz means the xyz th kind of piece where there are up to only 7 different kinds of pieces of a color. Thus the encodings used are from 1 to 7.
- Algorithm Find_PCES(color c)
 - // find all pieces of color c
 - $i = 0$
 - while $W_c \neq 0$ do
 - ▷ $a = TZCNT(W_c)$
 - ▷ $a = a \bmod 3$
 - ▷ $W_c = W_c$ right shift a bits // find next piece
 - ▷ $m[i++] = W_c \& 07$ // gives a piece of color c
 - ▷ $W_c \& = (07)$ // mask off the lowest 3 bits
 - return m

Example III

- In Othello, how to pack information in a column in a continuous sequence of cells?
 - Problem:
 - ▷ The board of Othello is a 8 by 8 rectangle. Assume we use a word to represent the board and use the row-major ordering, then cells in a column are non-adjacent.
 - ▷ Example: The first (leftmost) column are numbered 0, 8, 16, 24, 32, 40, 48, and 56 in a row-major ordering.
 - Encoding:
 - ▷ Assume you have a hardware word W of 64 bits.
 - ▷ W_b and W_w are words for black and white stones respectively.
 - ▷ 0 means empty or other color.
 - ▷ $(W_b|W_w)$ gives the word for empty spaces.
- Algorithm Find_Column(color c , int idx)
 - // pack information in column idx into adjacent bits
 - // Loc is an array which gives the masks of bits in column idx
 - $Mask = Loc[idx]$
 - $W = PEXT(W_c, Mask)$
 - return W

Comments

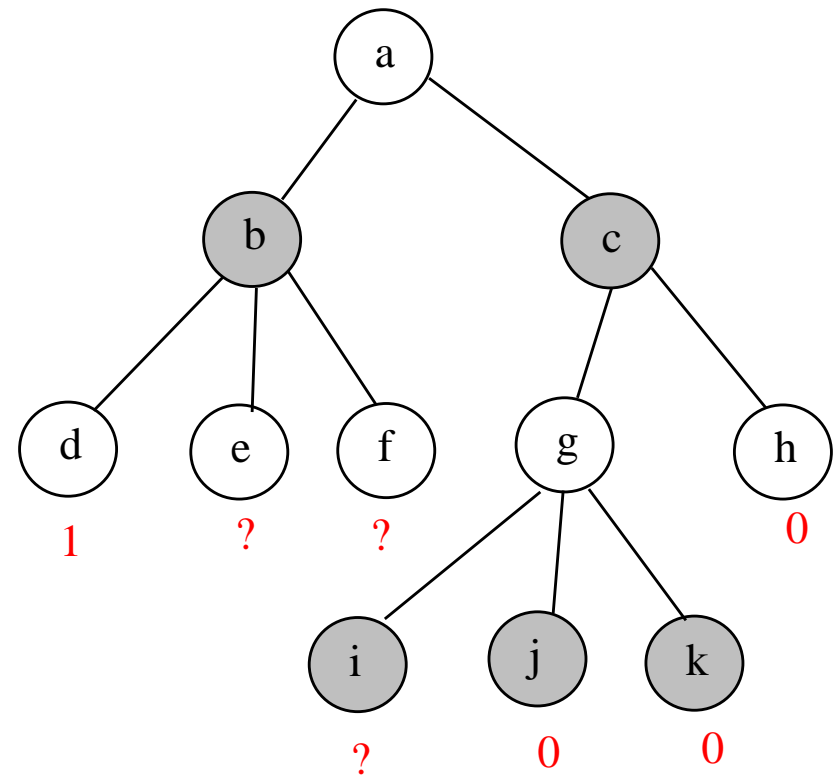
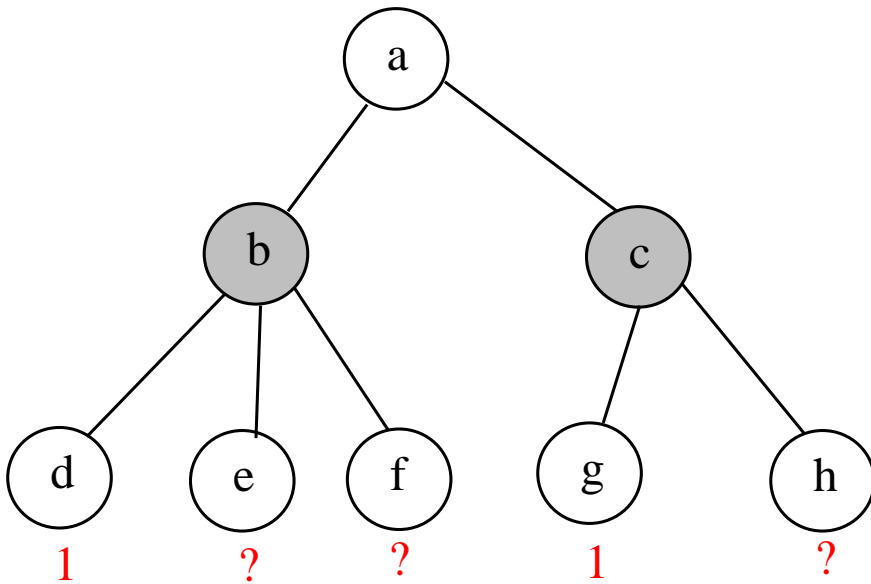
- Read carefully the instruction set of the CPU used to find out any special SIMD operations that are or aren't provided.
- The speedup is a lot, sometimes more than 50 times, if the encoding used is good [Browne 2014].

Proof number search

- Consider the case of a 2-player game tree with either 0 or 1 on the leaves.
 - win, or not win which is lose or draw;
 - lose, or not lose which is win or draw;
 - Call this a **binary valued game tree**.
- If the game tree is known as well as the values of some leaves are known, can you make use of this information to search this game tree faster?
 - The value of the root is either 0 or 1.
 - If a branch of the root returns 1, then we know for sure the value of the root is 1.
 - The value of the root is 0 only when all branches of the root returns 0.
 - An AND-OR game tree search.

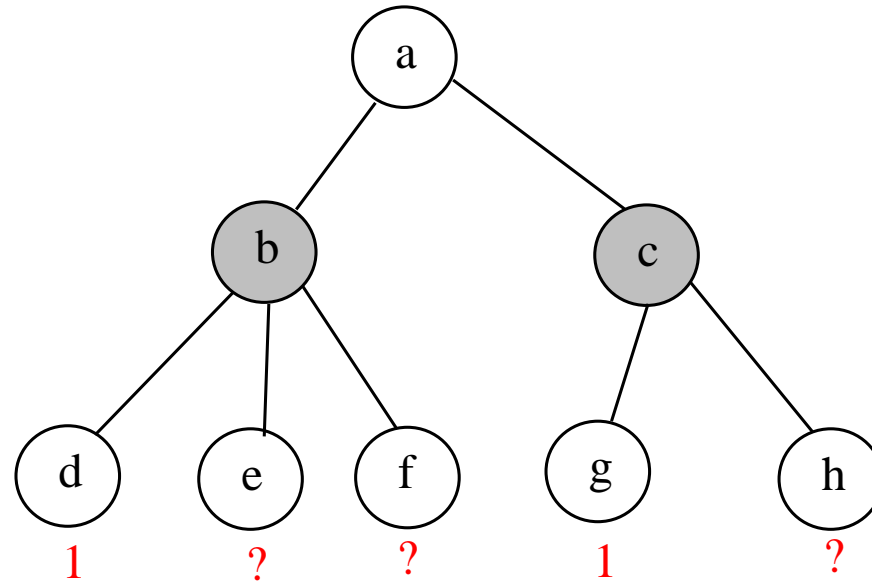
Which node to search next?

- A **most proving node** for a node u : a descendent node if its value is 1, then the value of u is 1.
- A **most disproving node** for a node u : a descendent node if its value is 0, then the value of u is 0.



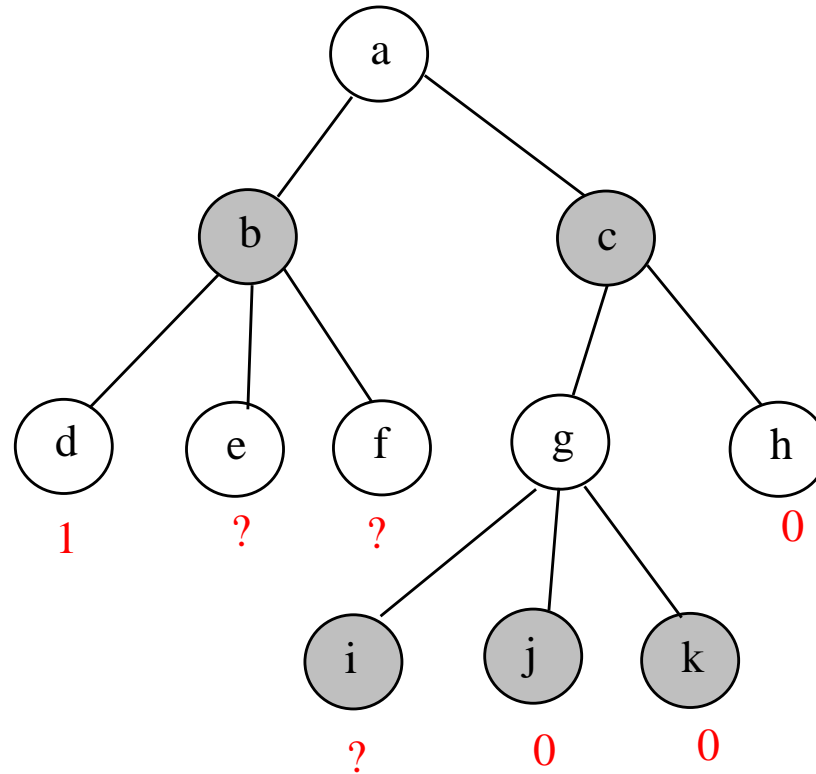
Most proving node

- Node h is a most proving node for a .



Most disproving node

- Node e or f is a most disproving node for a .



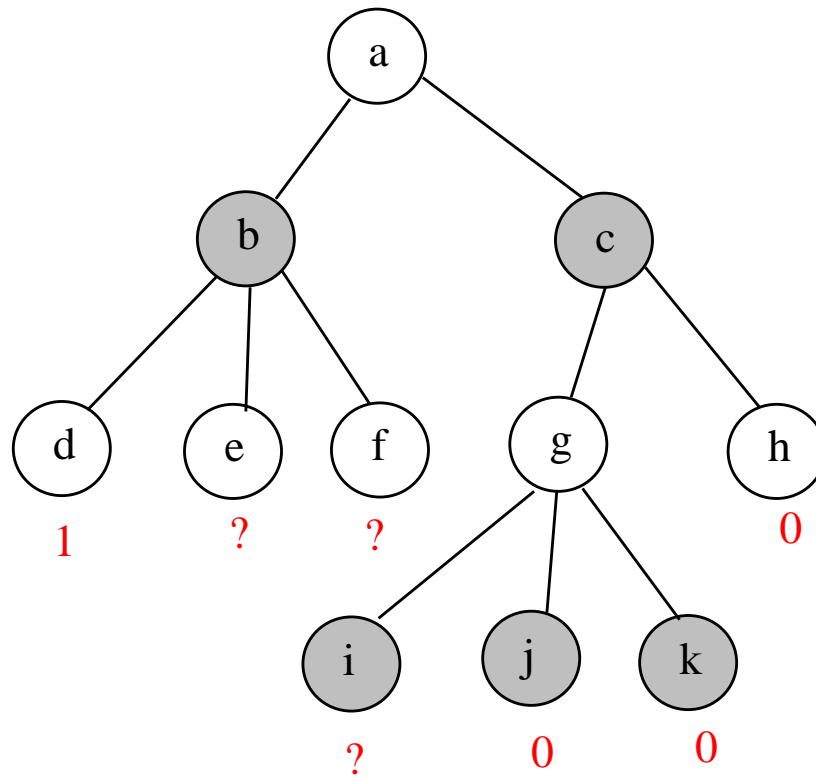
Proof or Disproof Number

- Assign a **proof number** and a **disproof number** to each node u in a binary valued game tree.
 - $proof(u)$: the minimum number of **leaves** needed to visited in order for the value of u to be 1.
 - $disproof(u)$: the minimum number of **leaves** needed to visited in order for the value of u to be 0.
- The definition implies a bottom-up ordering.

Proof number

- Proof number for the root a is 2.

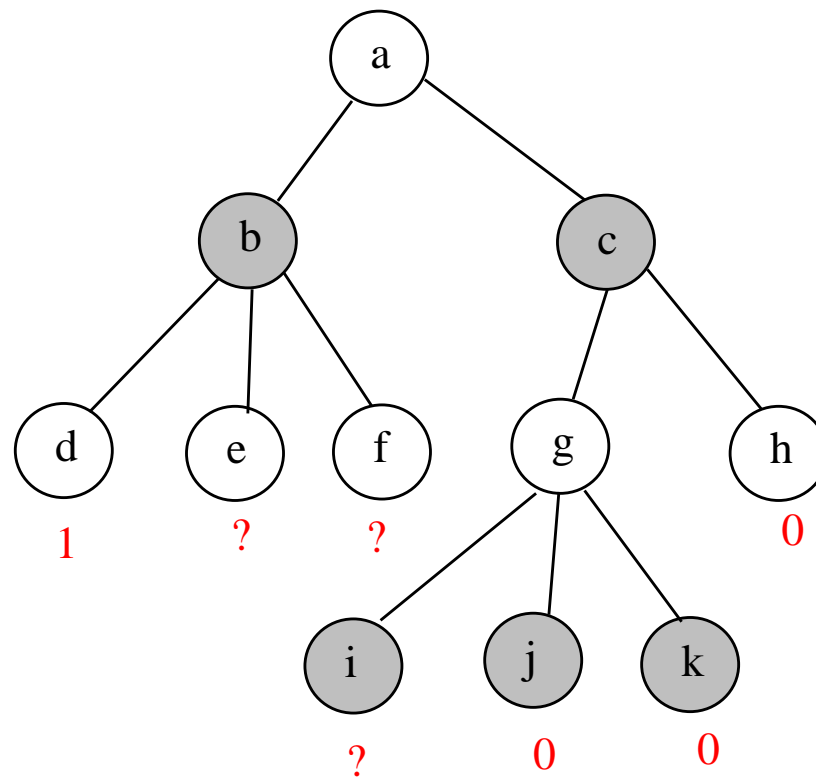
▷ Need to at least prove e and f .



Disproof number

- Disproof number for the root a is 2.

▷ Need to at least disprove i , and either e or f .



Proof Number: Definition

- u is a leaf:
 - If $value(u)$ is unknown, then $proof(u)$ is the cost of evaluating u .
 - If $value(u)$ is 1, then $proof(u) = 0$.
 - If $value(u)$ is 0, then $proof(u) = \infty$.
- u is an internal node with all of the children u_1, \dots, u_b :
 - if u is a MAX node,

$$proof(u) = \min_{i=1}^{i=b} proof(u_i);$$

- if u is a MIN node,

$$proof(u) = \sum_{i=1}^{i=b} proof(u_i).$$

Disproof Number: Definition

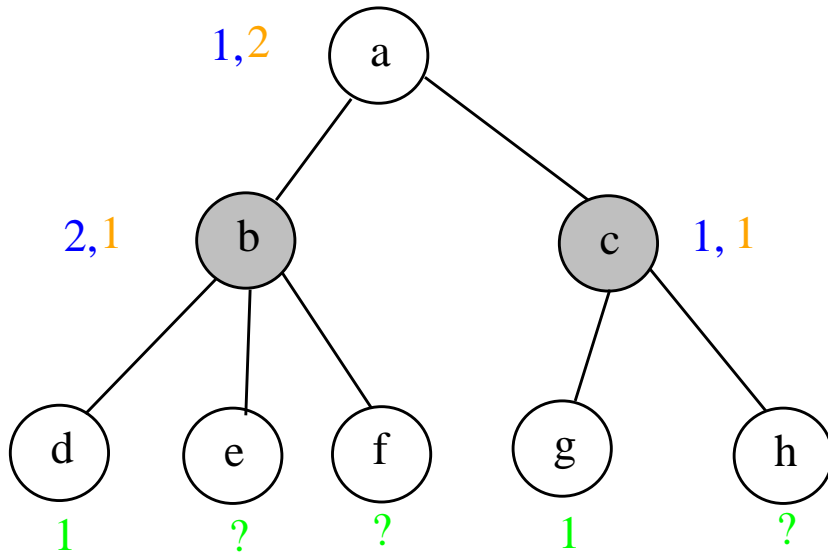
- u is a leaf:
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 - If $value(u)$ is 1, then $disproof(u) = \infty$.
 - If $value(u)$ is 0, then $disproof(u) = 0$.
- u is an internal node with all of the children u_1, \dots, u_b :
 - if u is a MAX node,

$$disproof(u) = \sum_{i=1}^{i=b} disproof(u_i);$$

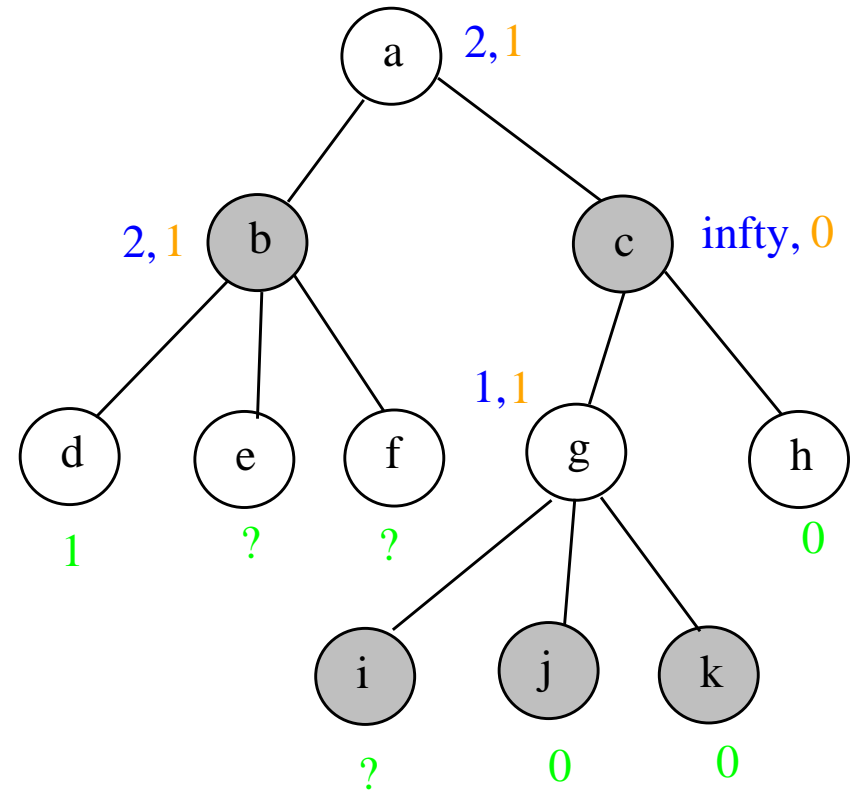
- if u is a MIN node,

$$disproof(u) = \min_{i=1}^{i=b} disproof(u_i).$$

Illustrations



proof number, disproof number



proof number, disproof number

How these numbers are used (1/2)

■ Scenario:

- For example, the tree T represents an open game tree or an endgame tree.
 - ▷ *If T is an open game tree, then maybe it is asked to prove or disprove a certain open game is win.*
 - ▷ *If T is an endgame tree, then maybe it is asked to prove or disprove a certain endgame is win o loss.*
 - ▷ *Each leaf takes a lot of time to evaluate.*
 - ▷ *We need to prove or disprove the tree using as few time as possible.*
- Depend on the results we have so far, pick a leaf to prove or disprove.

■ Goal: solve as few leaves as possible so that in the resulting tree, either $proof(root)$ or $disproof(root)$ becomes 0.

- If $proof(root) = 0$, then the tree is proved.
- If $disproof(root) = 0$, then the tree is disproved.

■ Need to be able to update these numbers on the fly.

How these numbers are used (2/2)

- **Let** $GV = \min\{proof(root), disproof(root)\}$.
 - GT is “prove” if $GV = proof(root)$, which means we try to prove it.
 - GT is “disprove” if $GV = disproof(root)$, which means we try to disprove it.
 - In the case of $proof(root) = disproof(root)$, we set GT to “prove” for convenience.
- **From the root, we search for a leaf whose value is unknown.**
 - The leaf found is a **most proving** node if GT is “prove”, or a **most disproving** node if GT is “disprove”.
 - To find such a leaf, we start from the root downwards recursively as follows.
 - ▷ *If we have reached a leaf, then stop.*
 - ▷ *If GT is “prove”, then pick a child with the least proof number for a MAX node, and any node that has a chance to be proved for a MIN node.*
 - ▷ *If GT is “disprove”, then pick a child with the least disproof number for a MIN node, and any node that has a chance to be disproved for a MAX node.*

PN-search: algorithm (1/2)

- **{* Compute and update proof and disproof numbers of the root in a bottom up fashion until it is proved or disproved. *}**
- *loop:*
 - **If $proof(root) = 0$ or $disproof(root) = 0$, then we are done, otherwise**
 - ▷ *$proof(root) \leq disproof(root)$: we try to prove it.*
 - ▷ *$proof(root) > disproof(root)$: we try to disprove it.*
 - **$u \leftarrow root$; {* find a leaf to prove or disprove *}**
 - **if we try to prove, then**
 - ▷ *while u is not a leaf do*
 - ▷ *if u is a MAX node, then*
 - $u \leftarrow$ leftmost child of u with the smallest non-zero proof number;*
 - ▷ *else if u is a MIN node, then*
 - $u \leftarrow$ leftmost child of u with a non-zero proof number;*
 - **else if we try to disprove, then**
 - ▷ *while u is not a leaf do*
 - ▷ *if u is a MAX node, then*
 - $u \leftarrow$ leftmost child of u with a non-zero disproof number;*
 - ▷ *else if u is a MIN node, then*
 - $u \leftarrow$ leftmost child of u with the smallest non-zero disproof number;*

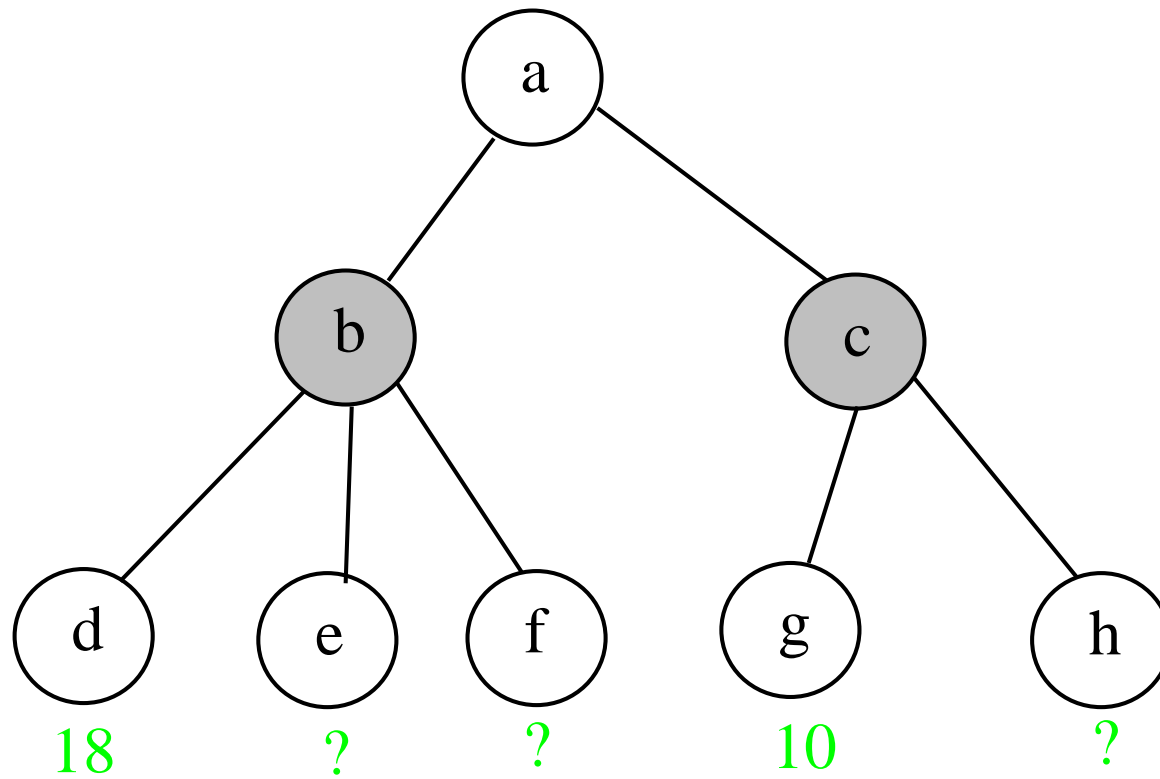
PN-search: algorithm (2/2)

- **{* Continued from the last page *}**
 - solve u ;
 - repeat **{* bottom up updating the values ***
 - ▷ *update $proof(u)$ and $disproof(u)$*
 - ▷ $u \leftarrow u$'s parent
 - until u is the root
 - go to *loop*;

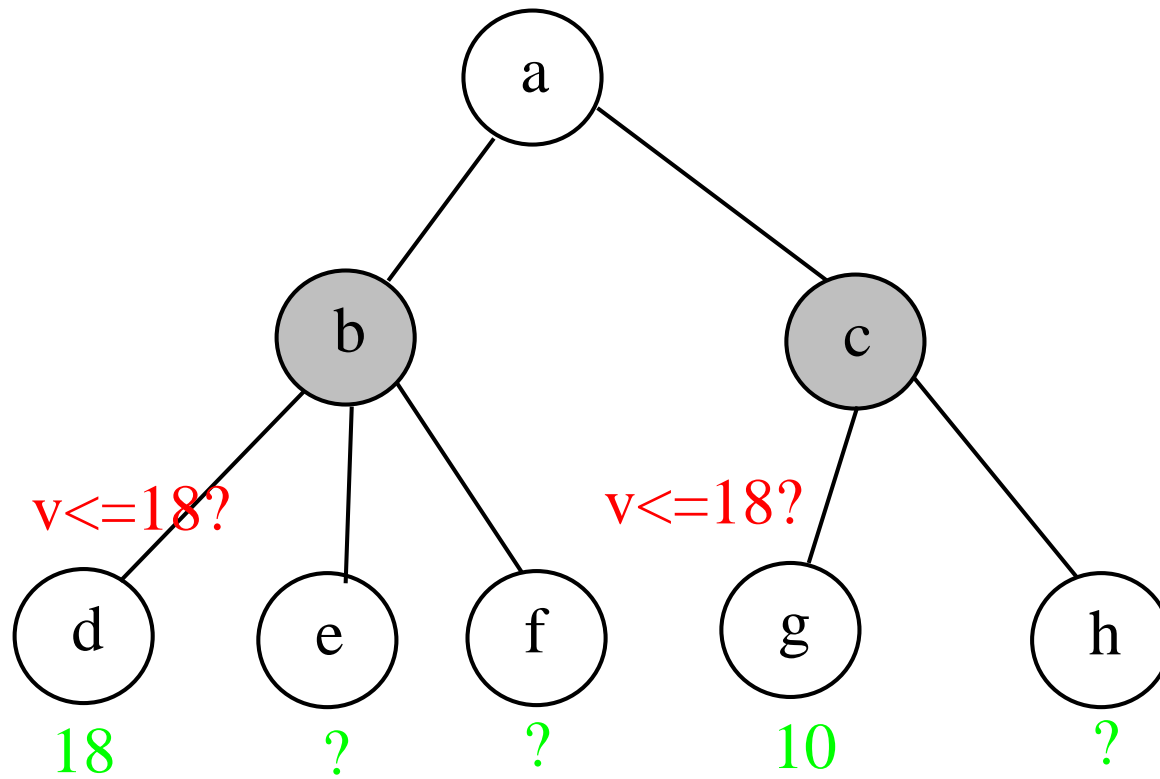
Multi-Valued game Tree

- The values of the leaves may not be binary.
 - Assume the values are non-negative integers.
 - Note: it can be in any finite countable domain.
- Revision of the proof and disproof numbers.
 - $proof_v(u)$: the minimum number of leaves needed to visited in order for the value of u to $\geq v$.
 - ▷ $proof(u) \equiv proof_1(u)$.
 - $disproof_v(u)$: the minimum number of leaves needed to visited in order for the value of u to $< v$.
 - ▷ $disproof(u) \equiv disproof_1(u)$.

Illustration



Illustration



Multi-Valued proof number

- u is a leaf:
 - If $value(u)$ is unknown, then $proof_v(u)$ is cost of evaluating u .
 - If $value(u) \geq v$, then $proof_v(u) = 0$.
 - If $value(u) < v$, then $proof_v(u) = \infty$.
- u is an internal node with all of the children u_1, \dots, u_b :
 - if u is a MAX node,

$$proof_v(u) = \min_{i=1}^{i=b} proof_v(u_i);$$

- if u is a MIN node,

$$proof_v(u) = \sum_{i=1}^{i=b} proof_v(u_i).$$

Multi-Valued disproof number

- u is a leaf:
 - If $value(u)$ is unknown, then $disproof_v(u)$ is cost of evaluating u .
 - If $value(u) \geq v$, then $disproof_v(u) = \infty$.
 - If $value(u) < v$, then $disproof_v(u) = 0$.
- u is an internal node with all of the children u_1, \dots, u_b :
 - if u is a MAX node,

$$disproof_v(u) = \sum_{i=1}^{i=b} disproof_v(u_i);$$

- if u is a MIN node,

$$disproof_v(u) = \min_{i=1}^{i=b} disproof_v(u_i).$$

Revised PN-search(v): algorithm (1/2)

- **{* Compute and update $proof_v$ and $disproof_v$ numbers of the root in a bottom up fashion until it is proved or disproved. *}**
- *loop:*
 - **If $proof_v(root) = 0$ or $disproof_v(root) = 0$, then we are done, otherwise**
 - ▷ *$proof_v(root) \leq disproof_v(root)$: we try to prove it.*
 - ▷ *$proof_v(root) > disproof_v(root)$: we try to disprove it.*
 - **$u \leftarrow root$; {* find a leaf to prove or disprove *}**
 - **if we try to prove, then**
 - ▷ *while u is not a leaf do*
 - ▷ *if u is a MAX node, then*
 - $u \leftarrow$ leftmost child of u with the smallest non-zero $proof_v$ number;*
 - ▷ *else if u is a MIN node, then*
 - $u \leftarrow$ leftmost child of u with a non-zero $proof_v$ number;*
 - **else if we try to disprove, then**
 - ▷ *while u is not a leaf do*
 - ▷ *if u is a MAX node, then*
 - $u \leftarrow$ leftmost child of u with a non-zero $disproof_v$ number;*
 - ▷ *else if u is a MIN node, then*
 - $u \leftarrow$ leftmost child of u with the smallest non-zero $disproof_v$ number;*

PN-search: algorithm (2/2)

- **{* Continued from the last page *}**
 - solve u ;
 - repeat **{* bottom up updating the values ***
 - ▷ *update $proof_v(u)$ and $disproof_v(u)$*
 - ▷ *$u \leftarrow u$'s parent*
 - until u is the root
 - go to *loop*;

Multi-valued PN-search: algorithm

- When the values of the leaves are not binary, use an open value binary search to find an upper bound of the value.
 - Set the initial value of v to be 1.
 - *loop*: $\text{PN-search}(v)$
 - ▷ *Prove the value of the search tree is $\geq v$ or disprove it by showing it is $< v$.*
 - If it is proved, then double the value of v and go to *loop* again.
 - If it is disproved, then the true value of the tree is between $\lfloor v/2 \rfloor$ and $v - 1$.
 - **{* Use a binary search to find the exact returned value of the tree. *}**
 - $low \leftarrow \lfloor v/2 \rfloor$; $high \leftarrow v - 1$;
 - **while** $low \leq high$ **do**
 - ▷ *if $low = high$, then return low as the tree value*
 - ▷ *$mid \leftarrow \lfloor (low + high)/2 \rfloor$*
 - ▷ *$\text{PN-search}(mid)$*
 - ▷ *if it is disproved, then $high \leftarrow mid - 1$*
 - ▷ *else if it is proved, then $low \leftarrow mid$*

Comments

- Can be used to construct opening books.
- Appear to be good for searching certain types of game trees.
 - Find the easiest way to prove or disprove a conjecture.
 - A dynamic strategy depends on work has been done so far.
- Performance has nothing to do with move ordering.
 - Performances of most previous algorithms depend heavily on whether good move orderings can be found.
- Searching the “easiest” branch may not give you the best performance.
 - Performance depends on the value of each internal node.
- Commonly used in verifying conjectures, e.g., first-player win.
 - Partition the opening moves in a tree-like fashion.
 - Try to the “easiest” way to prove or disprove the given conjecture.
- Take into consideration the fact that some nodes may need more time to process than the other nodes.

More research topics

- **Does a variation of a game make it different?**
 - Whether Stalemate is draw or win in chess.
 - Japanese and Chinese rules in Go.
 - Chinese and Asia rules in Chinese chess.
 - ...
- **Why a position is easy or difficult to human players?**
 - Can be used in tutoring or better understanding of the game.

Unique features in games

- Games are used to model real-life problems.
- Do unique properties shown in games help modeling real applications?
 - Chinese chess
 - ▷ *Very complicated rules for loops: can be draw, win or loss.*
 - ▷ *The usage of cannons for attacking pieces that are blocked.*
 - Go: the rule of Ko to avoid short cycles, and the right to pass.
 - Chinese dark chess: a chance node that makes a deterministic ply first, and then followed by a random toss.
 - EWN: a chance node that makes a random toss first, and then followed with a deterministic ply later.
 - Shogi: the ability to capture an opponent's piece and turn it into your own.
 - Chess: stalemate is draw.
 - Promotion: a piece may turn into a more/less powerful one once it satisfies some pre-conditions.
 - ▷ *Chess*
 - ▷ *Shogi*
 - ▷ *Chinese chess: the mobility of a pawn is increased once it advances twice, but is decreased once it reaches the end of a column.*

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